USER GUIDE

ICM*flex*

Partial discharge and loss factor measurement system

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This manual supersedes all previous issues of this manual.

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Declaration of Conformity

Hereby, Megger declares that equipment manufactured by Power Diagnostix Instruments GmbH described in this user guide is in compliance with Directives 2014/30/EU, 2014/35/EU, and 2011/65/EU. Other equipment manufactured by Power Diagnostix Instruments GmbH described in this user guide is in compliance with Directive 2014/53/EU where it applies.

The full text of Megger Instruments EU declarations of conformity are available at the following internet address:

megger.com/eu-dofc

Contents

1. General

1.1 About this user guide

This user guide describes the hardware, software, commission, and operation of the ICM*flex* in its current version including all available configurations. Therefore, it must be ensured that this manual is accessible to authorised and trained operating personnel at all times. The operating personnel must read the manual carefully.

The manufacturer will not accept liability for any damage to persons or materials caused by a failure to observe the safety instructions contained in this manual.

Keep this manual for future reference until the product is disposed of.

National standards and regulations must be observed.

Some of the hardware features of the most recent versions are not available with earlier versions of the instrument. It is possible to upgrade most of the previous instruments to the features of the current instruments. Contact our support team via the Megger web site (www.megger.com) for details.

Software updates are available through Megger's sales department. Contact Megger for details.

1.2 Working with products from Megger

The generally valid electrical regulations of the country in which the device is installed and operated, as well as the existing national regulations for accident prevention and any internal regulations (work, operating, and safety regulations) of the operator must be observed.

After working on the system, it must be disconnected from the power supply and secured against being switched on again, discharged, earthed, and short-circuited.

1.3 Operating personnel

The system must only be commissioned and operated by authorised, qualified electricians. Under DIN VDE 0104 (EN 50191), DIN VDE 0105 (EN 50110), and accident prevention regulations, the term 'qualified electrician' refers to persons who are able to identify hazards based on their knowledge, experience, and knowledge of the relevant regulations.

Other persons must be kept away.

2. Instrument safety

These safety warnings must be read and understood before the instrument is used. Retain for future reference.

2.1 Warnings, cautions, and notes

Only qualified and trained operators should operate the device. Each operator must read and understand the following safety information and this user guide prior to operating the equipment. The safety precautions herein are not intended to replace the safety procedures of your company.

In particular, read and follow the information marked with the words **WARNING** and **CAUTION**. The word **WARNING** is reserved for conditions and actions that pose hazards to the user, while the word **CAUTION** is reserved for conditions and actions that may damage the instrument or its accessories, or that may lead to malfunction.

This user guide follows the internationally recognised definition. These instructions must be adhered to at all times.

Description
WARNING : Indicates a potentially dangerous situation which, if ignored, could lead to death, serious injury or health problems.
CAUTION : Indicates a situation which could lead to damage of the equipment or environment
NOTE : Indicates important instructions to be followed to perform the relevant process safely and efficiently.

Always obey the safety rules given with the warnings and in this v. Make sure to take care of the safety issues while performing field measurements. Never disregard safety considerations even under the time constraints frequently encountered during on-line and off-line tests on site.

WARNING:

- **Always provide solid grounding of the instrument and the coupling units. Never operate the instrument without protective grounding.**
- **Avoid working alone.**
- **Do not allow the instrument to be used if it is damaged or its safety is impaired.**
- **Inspect the ground leads and signal cables for continuity.**
- **Select the proper coupling circuit and connection for your application.**
- **Do not use the instrument in an environment that is at risk of explosion.**
- **Use the fibre optic link or the Bluetooth communication to operate the instrument.**

2.2 Safety, hazard, and warning symbols on the instrument

This paragraph details the various safety and hazard icons on the instrument's outer case.

Icon	Description
	Warning: High voltage, risk of electric shock
	Caution: Refer to user guide.
CE	EU conformity. Equipment complies with current EU directives.
UK CA	UK conformity. This equipment complies with current UK legislation.
	Do not dispose of in the normal waste stream.

2.3 Battery module warnings

- This instrument is provided with a battery module.
- Do not pierce, damage, disassemble, or modify the battery module. The battery module contains safety and protection devices which, if tampered with, may cause the battery to generate heat, to rupture, or to ignite.
- If a battery is suspected to be faulty, replace it with a Megger approved battery module.
- If an instrument is suspected to contain a faulty battery module, the module must be removed before the instrument is shipped.
- Do not ship a faulty battery module, either separately or connected to an instrument.

3. Health and safety recommendations

3.1 General safety procedures prior to testing

When working with high voltages, these topics need to be considered carefully prior to the measurement set-up and testing.

1. The operators must have read the safety instructions and met the local site safety requirements relating to health and possible hazards.
2. The sample to be tested must be offline, de-energised, and grounded.
3. Each operator has to check the safety conditions together with the person responsible on the site and pass the tagout/lockout procedure for the specimen to be tested.
4. After the tagout/lockout procedure, the specimen must be checked for the presence of voltage in conjunction with the person responsible on site by using a suitable HV tester.
5. The operator has to check for solid grounding together in conjunction with the person responsible on site.
6. After completing steps 1) to 5), the specimen is in a safe condition and may be connected to the test equipment.
7. Find a safe area as close as possible to the specimen terminals to install the equipment.
8. Apply demarcation around the whole measurement set-up and make use of a safety guard, if necessary.
9. Do not work alone.
10. Only authorised personnel are allowed to enter the demarcated test area.
11. Warn other people working close to the hazardous area before energising the test specimen.
12. Check the insulation resistance prior to applying external HV potential.
13. Remove the calibrator before applying any external high voltage.
14. When applying external high voltage, carefully increase the voltage while checking that the voltage and current stay within predefined limits.
15. Make sure that the sample is discharged after the external high voltage has been switched off.
16. Discharge and ground the test specimen with a grounding stick before changing or touching any HV connection.
17. The specimen is now in safe condition, and necessary changes to the set-up can be made safely.

Check Megger's detailed "Health and safety instructions and recommendations" in the case of any ambiguities regarding safety.

3.2 Health and safety risks

Incautious actions during testing can result in life-threatening hazards such as electrocution. Be aware that this risk applies not only to the operators but also to other people working close to the area under high voltage. Follow the necessary personal protection recommendations as mentioned above and in the detailed technical guide "Health and safety instructions and recommendations" so that testing can be performed safely.

A specimen under high voltage can produce Ozone due to the presence of partial discharge activity. The maximum permissible ozone concentration in the open air is fixed on 0.1 ppm (parts per million) in accordance with the European Health Commission. Inhalation of too much ozone can lead to severe lung problems in the short and/or long term. Make sure that the test area is sufficiently ventilated. When necessary, make use of personal protection equipment, and be aware of this health recommendation during testing.

3.3 Environmental conditions

Care must be taken to ensure that the area surrounding the test specimen is in sufficiently clean and dry condition before installing the equipment and starting the tests. We recommend considering particularly the temperature and relative humidity. Temperatures above 45 °C can directly affect the performance of the battery. Working in conditions of high humidity can lead to additional stray capacitances influencing the tan delta and capacitance values, as well as the partial discharge measurement. Always make sure that the equipment is clean and leave sufficient space between the parts under high voltage and any other objects nearby.

4. Principle of operation

The ICM*flex* is a unique measurement system that covers PD detection, PD fault location on cables, and tan delta measurements (standard ICM*flex*, only). It has been designed to simplify the operation and to combine different measuring tasks with one instrument. This new principle minimises testing and operation time, increases operator's safety, and guarantees the highest sensitivity and precision. Main users of these systems are:

- Service groups testing motors, generators, and associated accessories
- Service groups testing high voltage cables, termination, and joints
- Maintenance and repair shops
- High voltage laboratories
- Research and development departments

The system is mainly used for on-site testing but can also be used in laboratories and workshops. It operates with any fixed or portable high voltage power supply, such as transformers, hi-pots, resonant test systems, motor generator sets, and VLF systems (cos/square and sine waves). Megger offers complete systems as well as modular components.

A complete acquisition system is shown in Figure 1. It consists of a reference capacitor C_n, two shunt capacitors C_{sn} and C_{sx}, a decoupling circuit for PD measurement, and an acquisition box with battery module. For systems above 30 kV, the main box is surrounded by an aluminium electrode to smooth the electrical field. Communication between a computer and the instrument can be established via Bluetooth or via fibre optic serial bus. All measurement values are displayed by the ICM*flex* remote control software on the computer.

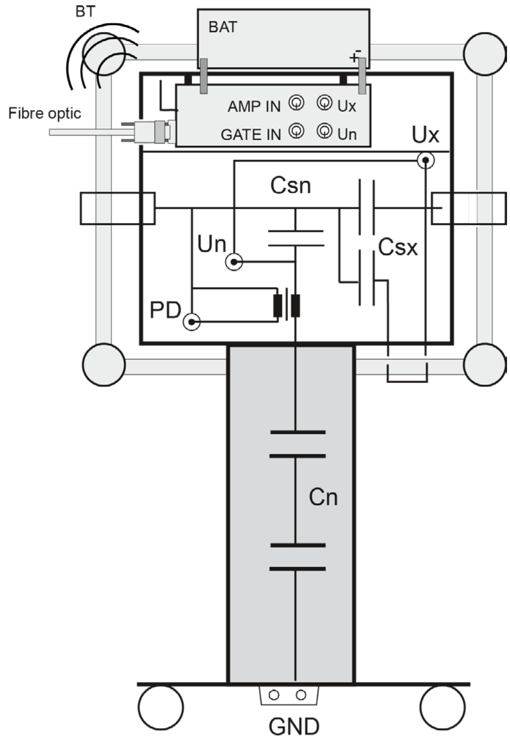


Figure 1: *Design of the ICMflex*

Two voltages can be measured with this system. U_x is taken from the capacitive divider between the external capacitance of the test object C_x and the internal shunt capacitor C_{sx}. The reference voltage U_n is provided by the capacitive divider C_n/C_{sn}. The waveform of both voltages is displayed together with the absolute values of U_{peak}, U RMS, and $U_{peak/sqrt2}$. The correlation of both signals gives further results, including the tan delta value, the power factor, and the capacitance C_x of the sample under test. Due to the high sampling rate of 100 kS/s and 16-bit A/D conversion, precision and accuracy can be guaranteed.

The high frequency PD signal is used for PD pattern acquisition as well as for PD fault location on cables, if needed. The PD scope has 8-bit resolution for phase and amplitude. The pulse count is up to 65536 (16 bits) per phase-amplitude position. The sensitivity of PD measurements depends strongly on the quality of the power supply. Megger offers various modular filter units to block noise generated by the source (see section 5.6). Furthermore, the instrument comes with a built-in gating input to trigger on HF pulses from the input side. External noise signals do not interfere with the measurements as all signals are directly taken at high voltage potential so there are no critical ground loops.

The following table shows the most common combinations and configurations of the ICM*flex*. Instruments for higher voltages and other configurations are available on request. Adaptable high voltage filters are available for all systems.

Rated voltage U_r (RMS)	Frequency range f	Reference capacitor C_n	Shunt capacitor C_{sn}	Shunt capacitor C_{sx}
30 kV	20–510 Hz (norm.) 0.02–0.1 Hz(VLF)	1000 pF	3 µF	10 µF/100 µF
30 kV	20–510 Hz (norm.) 0.02–0.1 Hz(VLF)	1000 pF	3 µF	40 µF/400 µF
50 kV	20–510 Hz (norm.) 0.02–0.1 Hz(VLF)	666 pF	2.5 µF	10 µF/100 µF
50 kV	20–510 Hz (norm.) 0.02–0.1 Hz(VLF)	666 pF	4 µF	40 µF/400 µF
100 kV	20–510 Hz (norm.) 0.02–0.1 Hz(VLF)	500 pF	10 µF	10 µF/100 µF
100 kV	20–510 Hz (norm.) 0.02–0.1 Hz(VLF)	500 pF	10 µF	40 µF/400 µF
150 kV	20–510 Hz (norm.) 0.02–0.1 Hz(VLF)	1000 pF	15 µF	10 µF/100 µF
150 kV	20–510 Hz (norm.) 0.02–0.1 Hz(VLF)	1000 pF	15 µF	40 µF/400 µF

Typical filter units are listed in the table below. Contact Megger if modified versions are needed.

Type	Rated voltage U_r (RMS)	Rated current I_r (RMS)	Frequency range f	Filter Configuration	Blocking capacitor C_b	Damping factor @100 kHz
T30/1	30 kV	1 A	0–300 Hz	L-C-L	10 nF	>100
T50/1	50 kV	1 A	0–300 Hz	L-C-L	10 nF	>100
T100/1	100 kV	1 A	0–300 Hz	L-C-L	10 nF	>100
T150/1	150 kV	1 A	0–300 Hz	L-C-L	10 nF	>100

Figure 2 shows a 50 kV set consisting of a T-filter T50/1 (left) and the ICM*flex* model for 50 kV (right).

Figure 2: *ICMflex (right) and T-filter (left) for 50 kV*

Based on application requirements, it is possible to order the ICM*flex* acquisition system in various configurations. The following table illustrates this modularity. Contact Megger to specify your required configuration.

Type	Comment
ICM*flex* Basic system	The basic system offers voltage measurement, frequency measurement, together with Bluetooth and fibre optic serial transmission ports. The black acquisition box is placed in the head of the grey case. The system is not usable without one of the following options.
ICM*flex* Option TD	This option enables all features for loss factor measurements. The system is supplied with customised shunt and reference capacitors. The software calculates the following values: C_x: Capacitance of the test object tan delta: Loss factor of the sample under test cos phi: Power factor of the sample under test Optionally, the system can be fitted with a C_{sx} bypass to avoid overstressing the shunt capacitor if the test object's capacitance is too high.
ICM*flex* Option PD	This option is needed if PD measurements are to be made for the test object. The system comes with a built-in measuring impedance on HV potential. The software displays all PD activities in a PD scope graph, allows PD pattern acquisition, and indicates the precise PD magnitude Q_p.
ICM*flex* Option LOC	This option can be chosen in addition to the PD option. A special high-speed sampling board with 16-bit 100 MS/s A/D converter enables pulse measurement vs. time. This option is mandatory for PD fault location on cables. The software offers a special TDR (Time Domain Reflectometry) graph and other evaluation tools.

5. Measurement set-up

5.1 Verifying the part list

Before commencing installation, check that all parts are available. The standard package consists of the these items:

- Acquisition unit ICM*flex*,
- HV filter (optional),
- Battery pack type BAT2A,
- Battery charger,
- Fibre optic cable (10 m); USB to Sub-D
- Computer including ICM*flex* software,
- PD calibrator CAL1B or similar including connection set (optional),
- Set of cables:
  - 0.6 m HV cable (grey) with multi-contact connectors (male/female),
  - 1.5 m HV extension cable (grey) with multi-contact connectors (male/female)
  - 1.0 m HV cable (grey) with multi-contact connector (female) at one end and clamp connector at the other end,
  - 1.0 m grounding lead (yellow/green) with multi-contact connectors (male/female),
  - 1.5 m grounding lead (yellow/green) with multi-contact connector (male) at one end and clamp connector at the other end,
  - 74 cm RG58 cable
- Set of spare connectors; type multi-contact (male),
- User guide.

Contact Megger for spare parts or updates.

5.2 High voltage cabling

A set of high voltage cables is shown in Figure 3.

Be aware that the high voltage cables supplied are non-shielded cables which must not touch or be close to ground potential. The insulation of the high voltage cables supplied by Megger can withstand a maximum voltage of 13.8 kV with direct contact to ground. Nevertheless, the cable must be installed at a safe distance from any grounded objects. If the cables are in direct contact with ground, surface discharge activity will start from 3 kV. Check Megger's detailed "Health and Safety Instructions and Recommendations". The minimum distances which must be observed in open air conditions, in relation to the applied voltage, are specified in Annex 3.

The cables can be used outdoors at voltages of up to 120 kV. Higher voltages cause audible corona discharges. The electric field is lower around the corona protection of ICM*flex*, high voltage filters, CSX900, or coupling capacitors, enabling the cables to be used there at voltages above 120 kV. In such cases, the components must be positioned in such a way that the cables do not protrude from this area of weaker electric field.

If the cable is terminated with a clamp, this clamp may only be used in an area with a low electric field.

Figure 3: *High voltage cables*

5.3 Battery

Before operation, ensure that the battery is full charged. To recharge the battery follow the steps below.

- Switch the BAT2A off and remove it from the ICM*flex*.
- Plug the charger into a socket, the LED of the charger will light up yellow.
- Connect the charger to the BAT2A, the LED will switch over to orange after a few seconds. This indicates that the BAT2A is being charged which will take about three hours for a completely discharged BAT2A.
- When the BAT2A is fully charged, the LED will light up green and the charge process is stopped automatically.

Figure 4: *BAT2A and battery charger*

NOTE : The BAT2A will warm up during the charging process, this is normal.

The BAT2A should be recharged every three months, even when it is not used.

5.4 Location

As mentioned above in the general procedure prior to installation, find a safe location close to the specimen to install the equipment. Ask for a fenced, delineated, or enclosed area, if required, as shown in Figure 5, and avoid environmental conditions with high relative humidity and extreme temperatures.

Figure 5: *MV cable testing on-site*

5.5 Parts of the ICM*flex* under high voltage potential

The ICM*flex* has a unique design concept. The entire acquisition unit is at high voltage potential right where the necessary signals are. This offers the advantage that no additional signal cables are needed. The filter units are constructed on the same principle. The parts that are at high voltage potential are marked with warning signs to prevent confusion during set-up (see Figure 6 in section 5.6).

The complete head box, including the corona cage surrounding the top of the reference capacitor and both MC connectors on the in- and output, is at high voltage potential. The bottom plate of the ICM*flex* and corresponding filter unit are at ground potential.

5.6 Connecting the ICM*flex*

Read the application guide for testing of medium and high voltage cables and rotating machines for specific set-up information. The main connections are explained below.

The appropriate connection of the HV source (HV transformer, resonance test set, VLF high potential) to the filter and/or ICM*flex* is sown on the top covers of both the filtering unit and the ICM*flex*. Follow the connection arrangements shown.

The HV cable of the power supply has to be connected to the female input connector of the filter (at the left-hand side of Figure 6) or, if a filter is not needed, directly to the input of the ICM*flex*. A connection needs to be provided from the male output connector of the filter (at the right-hand side of Figure 6) to the female connector of the ICM*flex*. Finally, the male connector of the ICM*flex* needs to be connected to the specimen. This can be a motor terminal, the conductor of a shielded high voltage cable or a stator bar. The interconnection between the filter and ICM*flex* is, of course, not needed if no filter is used.

Figure 6: *Filter connectors*

The coaxial output from the filter (left picture in Figure 7) is used for analogue noise gating. A noise decoupling circuit is directly built into the filter to capture any noise originating from the high voltage supply. A coaxial connection between the filter output and the ICM*flex* input (right picture in Figure 7) has to be established to use the gating option. Prevent direct contact between the coax cable and the high voltage cable connecting the filter and the ICM*flex*.

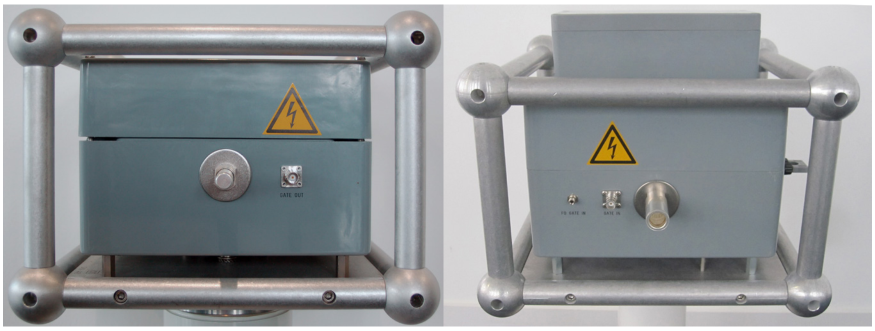


Figure 7: *Coaxial gating connector for filter (left) and ICMflex (right)*

CAUTION and WARNING: The GATE OUT of the HV filter may solely be connected to the GATE IN of the ICM*flex*. Connecting it to other instruments or even to earth will lead to the damage of the equipment. When the BNC gating cable is connected to the filter, its other end must not be left unconnected to prevent test personnel from touching the loose end of the cable.

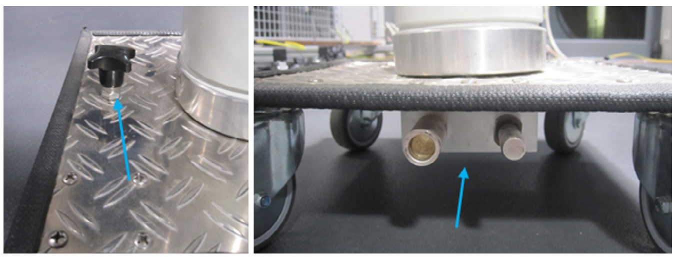


Figure 8: *Ground connection points*

The ground loop of the measuring set-up is very important. Poor grounding has a big influence on the sensitivity because of background noise. The main ground of the power supply has to be connected to the ground terminal of the filter unit or, if no filter is used, directly to the ICM*flex*. Connection points are provided on the metallic grounding plates, as shown in Figure 8. Connections can be made by using a cable lug or a multi-contact. Use the short cables supplied to interconnect the grounding of the filter and the grounding of the ICM*flex*. Avoid loops since these will act as an antennas and influence the noise behaviour. Finally, a connection, which should be as short as possible, must be established between the ICM*flex* and the main grounding of the test specimen. Choose a solid grounding connection and ensure good contact. Interconnection between the grounding of the filter and the ICM*flex* is not necessary if no filter is used. A typical test set-up is shown in Figure 10.

The most convenient way to communicate with the instrument is via the Bluetooth interfaceas this requires no additional cabling. However, if a Bluetooth connection cannot be established, it is possible to use the fibre optic serial link instead. The D-Sub female connector of the cable has to be connected to the male connector on the side of the ICM*flex* (as shown in Figure 9). The cable USB connector of the cable can be connected to any free USB port on the computer. As the fibre optic cable provides a galvanic separation from the high voltage potential, there is no risk to the operator.

CAUTION and WARNING: Never use a standard D-Sub cable that does not galvanic separation. This can result in damage to components and serious injury or death.

Figure 9: *SUB-D input connector*

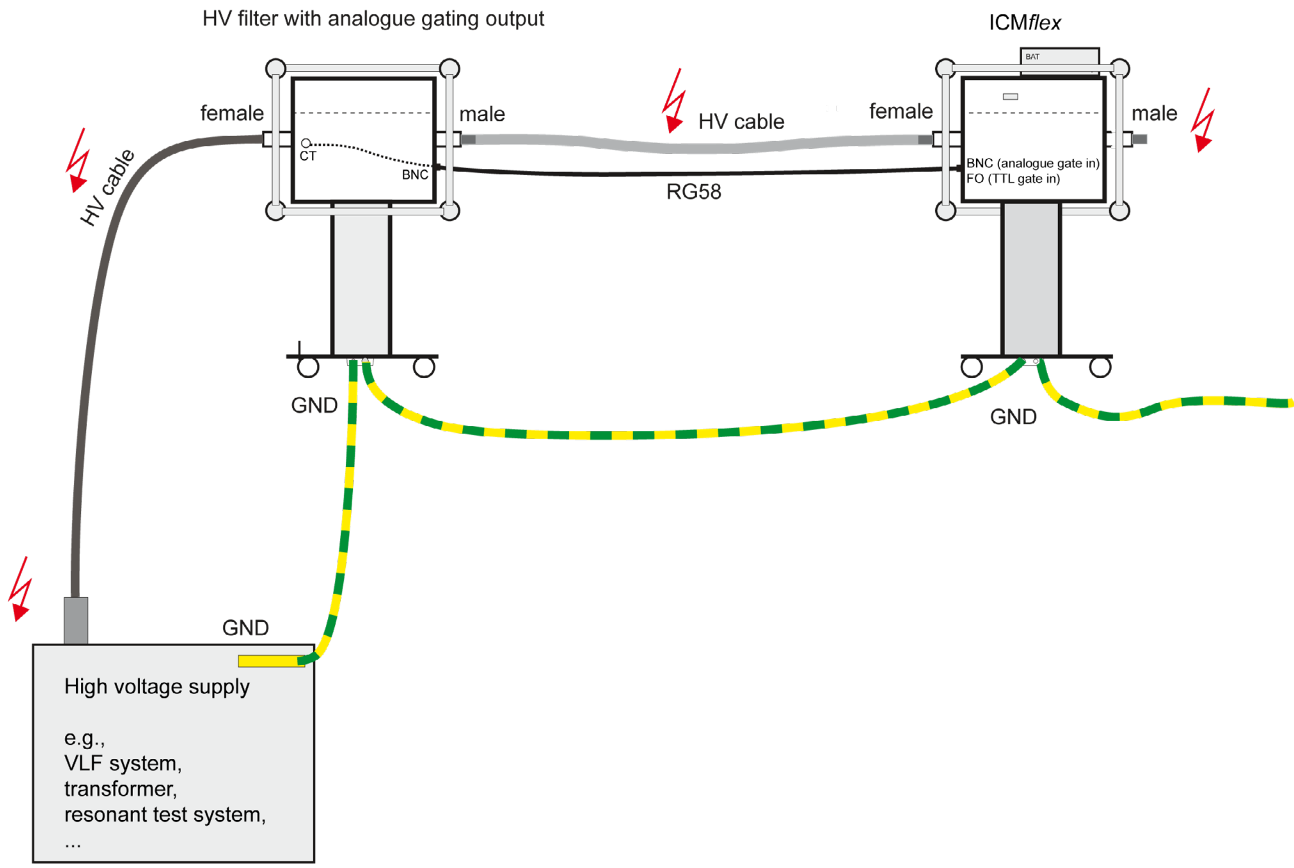


Figure 10: *General connection diagram for ICMflex*

6. Software and driver installation

The ICM*flex* is supplied with a Windows based software package on a USB drive. The software can be installed on Windows operating systems versions 10 and 11 with 32-bit or 64-bit architecture. If a computer is provided by Megger, the software and the instrument drivers are pre-installed and ready configured. In this case, no further action is needed but, in all other cases, the following preparations must be made.

6.1 Installing the ICM*flex* software

NOTE : Administrator rights are necessary to complete the installation of this software product. Contact your system administrator if you have insufficient rights on the target computer.

Start the setup.exe file that can be found within the ICM*flex* directory on the USB stick. If a new software version has been received as ZIP archive, unzip all files to a local directory on the target system first. After starting the setup.exe file, a window like the one shown in Figure 11 below will pop up.

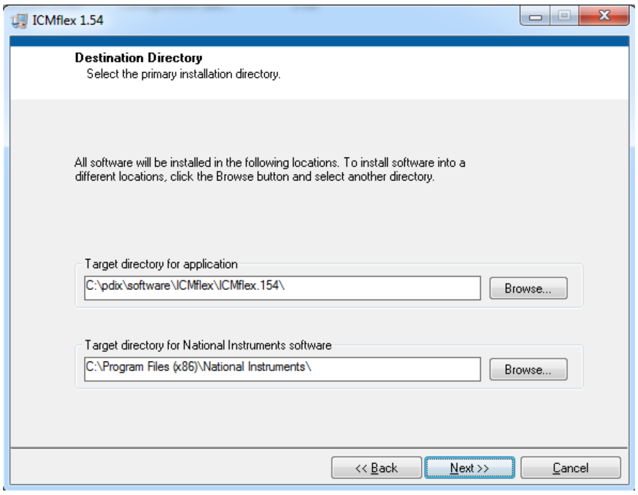


Figure 11: *Software installation setup*

Choose custom installation directories, if wanted, and click "Next". The installation kit automatically detects earlier versions and updates only these with newer files provided by this release. This software has been developed under National Instruments LabWindows/CVI. Therefore, additional DLLs and libraries will be installed automatically within the Windows system directory.

After finalising the software installation procedure, the system restarts automatically.

The ICM*flex* software can be started directly by clicking on the appropriate icon (as shown in Figure 12) on the desktop. Before starting to communicate with the instrument, however, further preparations must be completed.

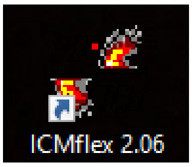


Figure 12:
Desktop icon

6.2 Setting up a Bluetooth COM port

All Bluetooth devices on computer systems can provide so-called virtual COM ports. These COM ports are used to establish a connection with the ICM*flex*. Standard laptops usually come with built-in Bluetooth interfaces. If such an interface is not available, it is possible to use external USB-Bluetooth devices. Megger can provide these devices for USB, PCI, and other interfaces. The Bluetooth interface on any computer provides an automatic scanning function. Start this function to find the ICM*flex* Bluetooth device.

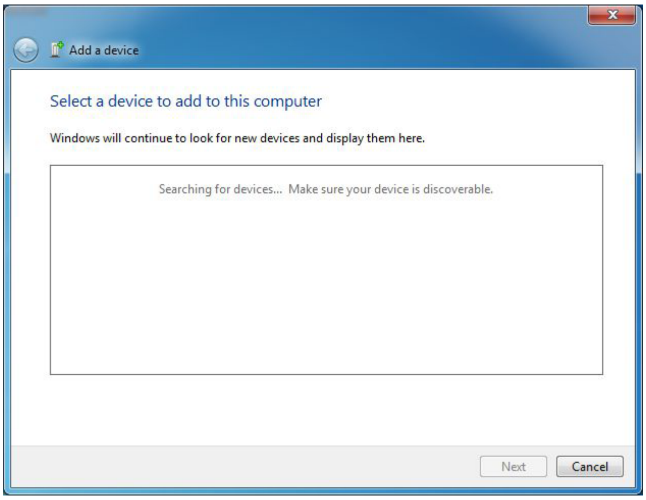


Figure 13: *Bluetooth connection wizard*

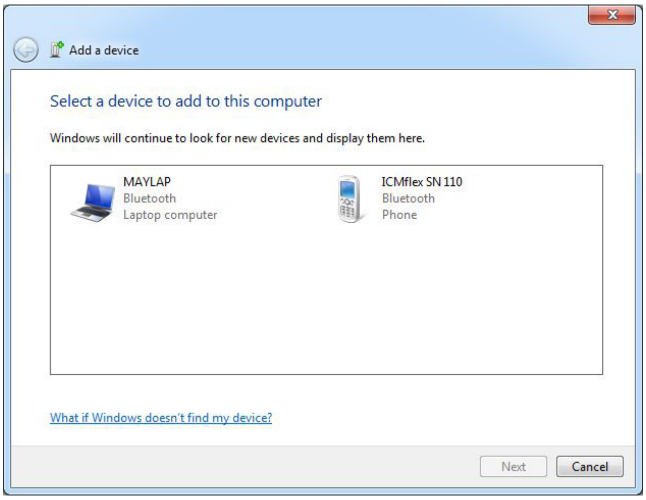


Figure 14: *Adding a Bluetooth device*

The express mode will guide you through this set-up (Figure 13). Click “Next”. The search routine can take a few minutes. A pop-up window will display all devices found in range (Figure 14). Select the “ICM*flex*” entry and continue the installation procedure (Figure 15).

It is mandatory to set the device code (Figure 16) for the ICM*flex* connection to “0000”.

Figure 15: *Bluetooth device successfully added*

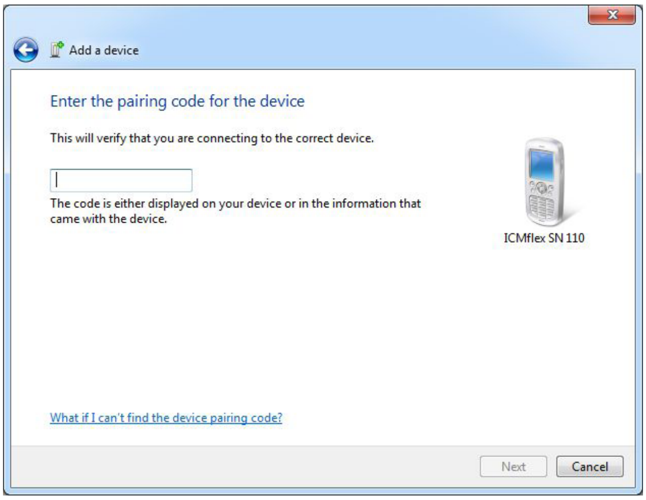


Figure 16: *Entering pairing code*

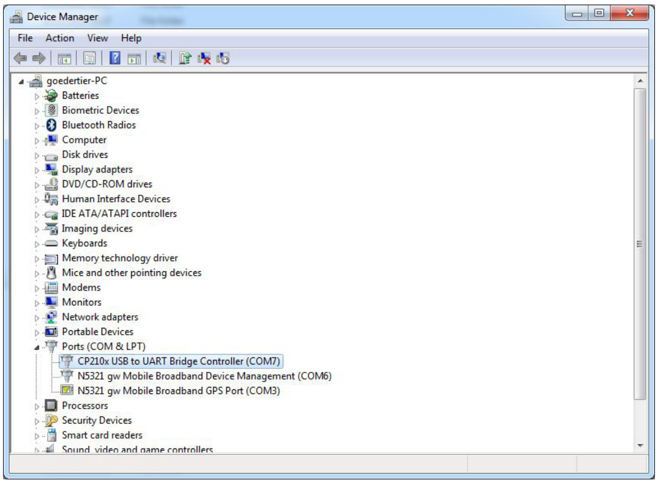


Figure 17: *Windows Device Manager*

If, successful, the Windows hardware manager will automatically install a virtual COM port for the new device. Typically, two COM ports will be installed for the ICM*flex* as shown in Figure 17. Enable both with the ICM*flex* software interface settings as described in section 7.2.

6.3 Setting up a fibre optic communication port (USB serial COM)

A special fibre optic cable is supplied with the ICM*flex*. The D-Sub male connector has to be connected to the COM TTL female connector of the instrument box. The case of the D-sub plug contains the hard wired connection to the fibre optic converter. The default length of this cable is 10 meters. Individual lengths can be supplied on demand. The side with the USB-A connector contains a fibre optic to USB converter. This end can be connected to any free USB port of the laptop or PC. The driver for the fibre optic cable will be installed with the software. Do not connect the cable to the computer before the software is installed! If the driver is not installed correctly, Windows will start the hardware installation wizard (as shown in Figure 18) when connecting the USB connector to the computer for the first time.

To guarantee correct installation, it is recommended to perform the installation procedure while being connected to the internet. The Windows hardware manager searches the Windows driver library on the internet to find a suitable driver for this new device. Contact Megger in case of problems.

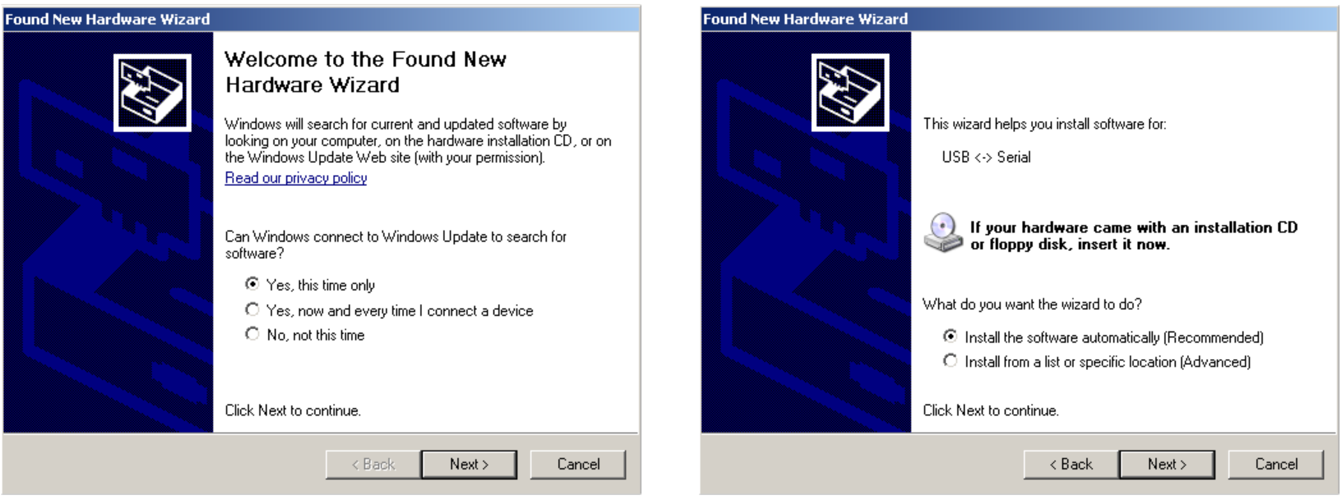


Figure 18: *Driver installation wizard*

If the computer does not recognise the cable, the drivers need to be installed manually. Go to the device manager and select the related COM port. After a right mouse click, select “Update driver”. A window similar to that in Figure 18 will pop up. Find the driver in a subfolder named “USB Driver\CP210x” in your ICM*flex* software installation directory, e.g.,

C:\pdix\Software\ICM*flex*\ICM*flex*.186]\USB Driver\CP210x.

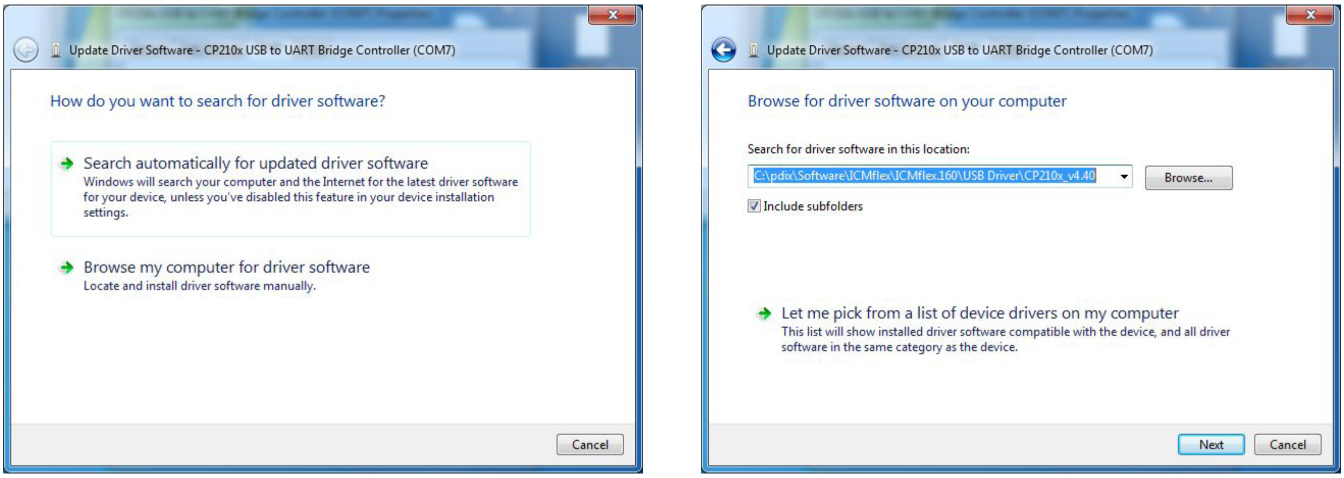


Figure 19: *Driver installation*

This procedure must be performed twice: the first time for the USB cable itself and the second time for the cable converter.

The setup routine will automatically install the USB serial COM port, if found, and a new COM port (e.g., COM7) will be displayed by the device manager.

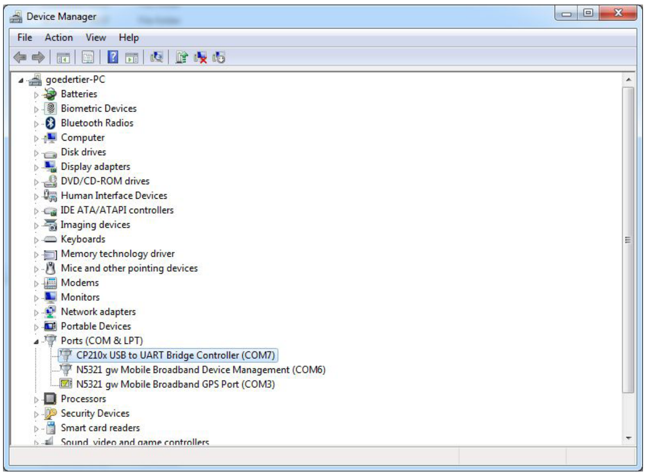


Figure 20: *Device Manager*

Note that the COM port number has to be enabled within the interface settings of the ICM*flex* software (see section 7.2). After restarting computer, the software will automatically search for the COM port in use. If the software can’t find the COM port, check manually in the device manager as shown in Figure 20.

7. ICM*flex* software

7.1 First steps

The ICM*flex* software has a default factory settings at start-up. All settings will be saved when closing the application. When they are changed, settings affecting the acquisition circuit are sent to the ICM*flex* acquisition box. The instrument acts as slave, and the software acts as master.

Note: If the application window appears very small when started on a PC with Windows 10 or Windows 11, refer to section "11.3 Troubleshooting" on page 60.

If not yet connected to an instrument the software displays all data for the last measurement. This data is saved in an .flx file into a specified storage directory, e.g.,

c:\pdix\software\ICM*flex*\ICM*flex*.154\icmflex.flx

All optional program preferences like colours, interface settings, etc. are stored in a file called

c:\pdix\software\ICM*flex*\ICM*flex*.154\icmflex.ini

The main program appears as a shortcut link on the desktop, in the "Start"->"Programs" folder, and can be started directly from the installation directory. A screenshot of the main program with an ICM*flex* connected is shown in Figure 21.

c:\pdix\software\ICM*flex*\ICM*flex*.154\icmflex.exe

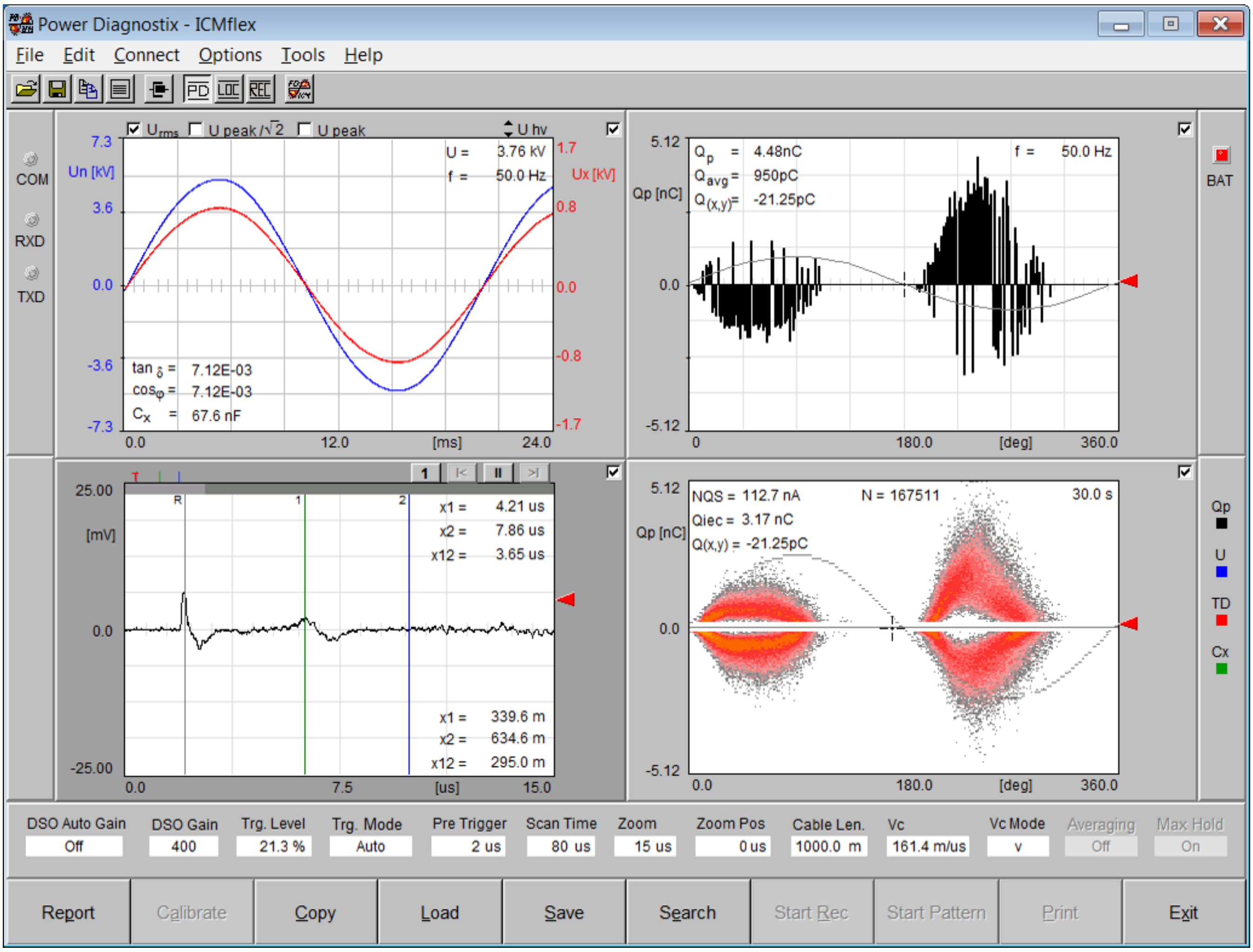


Figure 21: *Main screen of the ICMflex software*

7.2 Connecting to the instrument

Before connecting to the instrument, it is recommended to check the COM port settings in the menu "Options"->"Interface Settings" as shown in Figure 22. Enable the port number specified for Bluetooth or fibre optic communication (see sections 6.2 and 6.3). Normally, the software automatically searches the instrument when the check box "Search Device at Startup" is selected. The COM port in use will be indicated by the * symbol. If this is not the case, the correct settings can be found with the Windows device manager.

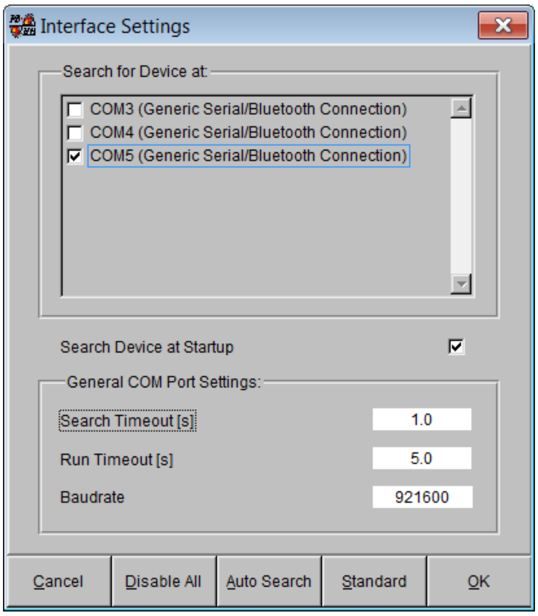


Figure 22: *Interface settings*

Make sure that only one COM port is enabled. First, disable all ports by pressing the "Disable All" button. Then select the COM port from the list by clicking the corresponding checkbox. All other settings remain unchanged and do not need to be modified during standard operation.

All changes will become active after closing this panel by pressing the "OK" button. The "Cancel" function closes this window without any changes to the values. Pressing the "Standard" button enables the default COM ports and sets all timeouts back to these default values:

Search Timeout: 2 s

Run Timeout: 5 s

Baud rate: 921600 kBit/s

To connect with an instrument, press the "Search" button at the bottom of the main screen of the software or by selecting the "Search" function from the "Connect" menu. Important functions can also be activated by shortcuts. For the search routine, press the function key F5.

The search pop-up window shows if an instrument was found and successfully connected.

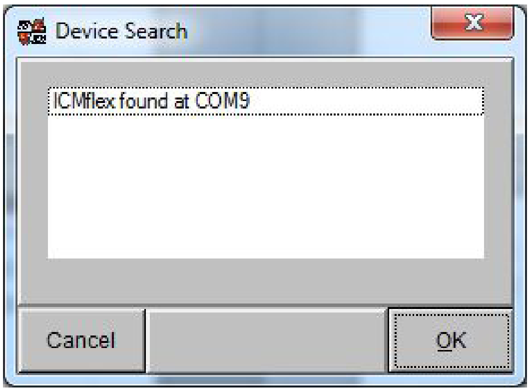


Figure 23: *Searching for ICMflex COM ports*

7.3 Firmware updates and configuration files

After a software upgrade, a pop-up window may appear indicating the availability of a new firmware version (Figure 24). Do not hesitate to install the update, as it will include important enhancements for the unit.

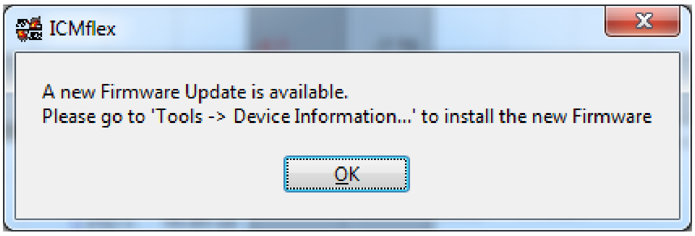


Figure 24: *New firmware pop-up*

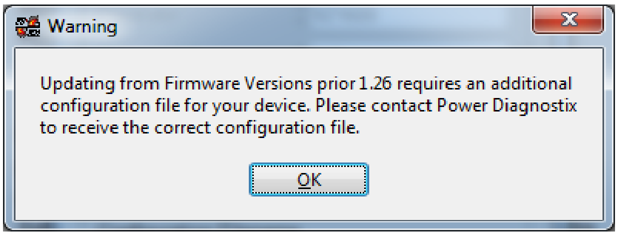


Figure 25: *Configuration file pop-up*

Updates of firmware version ≥ 1.26 require a configuration file after the first launch. Normally, the latest ICM*flex* units are configured at the factory. If you update from an older version, a pop-up will appear as shown in Figure 25. To receive a configuration file for your device, contact our support team via the contact form of the Megger web site (www.megger.com) and quote the instrument’s serial number.

Once stored in the device, this configuration does not need to be repeated. The configuration file contains all important information about the instrument, such as the capacitor values according to the voltage calibration, Cn and Csn and the shunt capacitor Csx high and low. These settings can be cross checked via the menu “Edit”->”Advanced Settings” (Figure 26).

Firmware and configuration files can be uploaded using the device update function, available via the menu “Tools”->”Device Information”. A screenshot of the update tool is shown in Figure 27. A firmware file is identified by the extension .bin, a configuration file by the extension .cfg.

After a successful upload, the communication with the instrument will be briefly interrupted and then automatically re-established after rebooting the acquisition box.

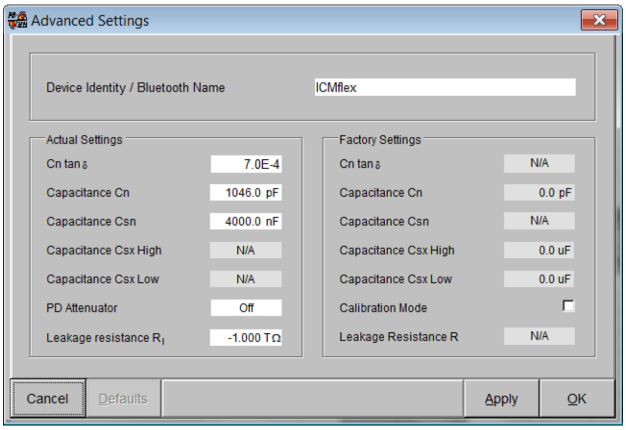


Figure 26: *Advanced settings*

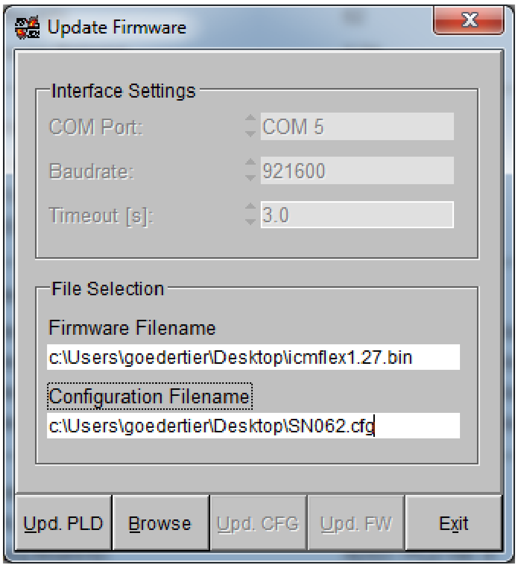


Figure 27: *Firmware update window*

The device configuration panel shows detailed information about the instrument, e.g., the serial number and installed firmware version. To access this information, connect to the instrument and open the device configuration panel. A screenshot of the device configuration is shown in Figure 28. Since the instrument can be ordered in different configurations, check that all features are available as expected, e.g.,

- Partial discharge measurement
- Partial discharge fault location for cables
- Tan delta and loss factor measurements including voltage and frequency acquisition

Besides the instrument options, the information panel also shows the battery monitoring parameters such as the battery voltage, current, charge, and battery lifetime.

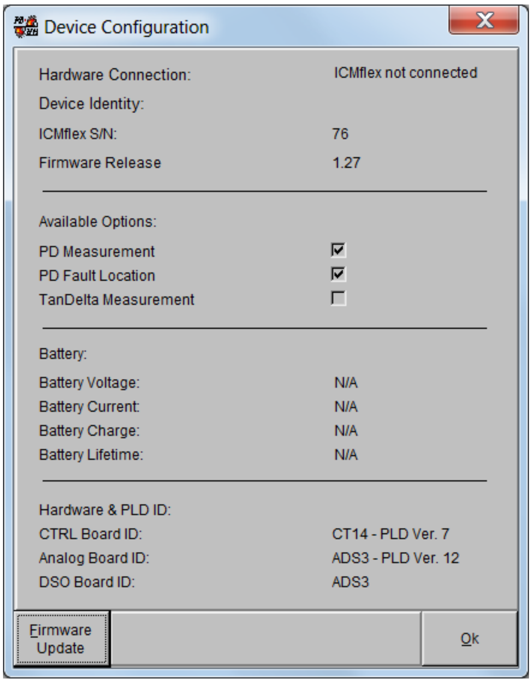


Figure 28: *Device configuration panel*

7.4 Principle of operation

The ICM*flex* software has a typical front-panel system that gives access to all main functions, graphs, and settings. This panel, as shown on the next page, is divided into four main areas. These areas vary depending on the display mode that is chosen. Available display modes are PD, LOC, and REC.

7.4.1 PD display mode

The PD display mode shown in Figure 29 is mainly used for PD measurements and is required for calibration of the apparent charge's amplitude. For cable testing, the cable length and pulse velocity can also be calibrated in this screen.

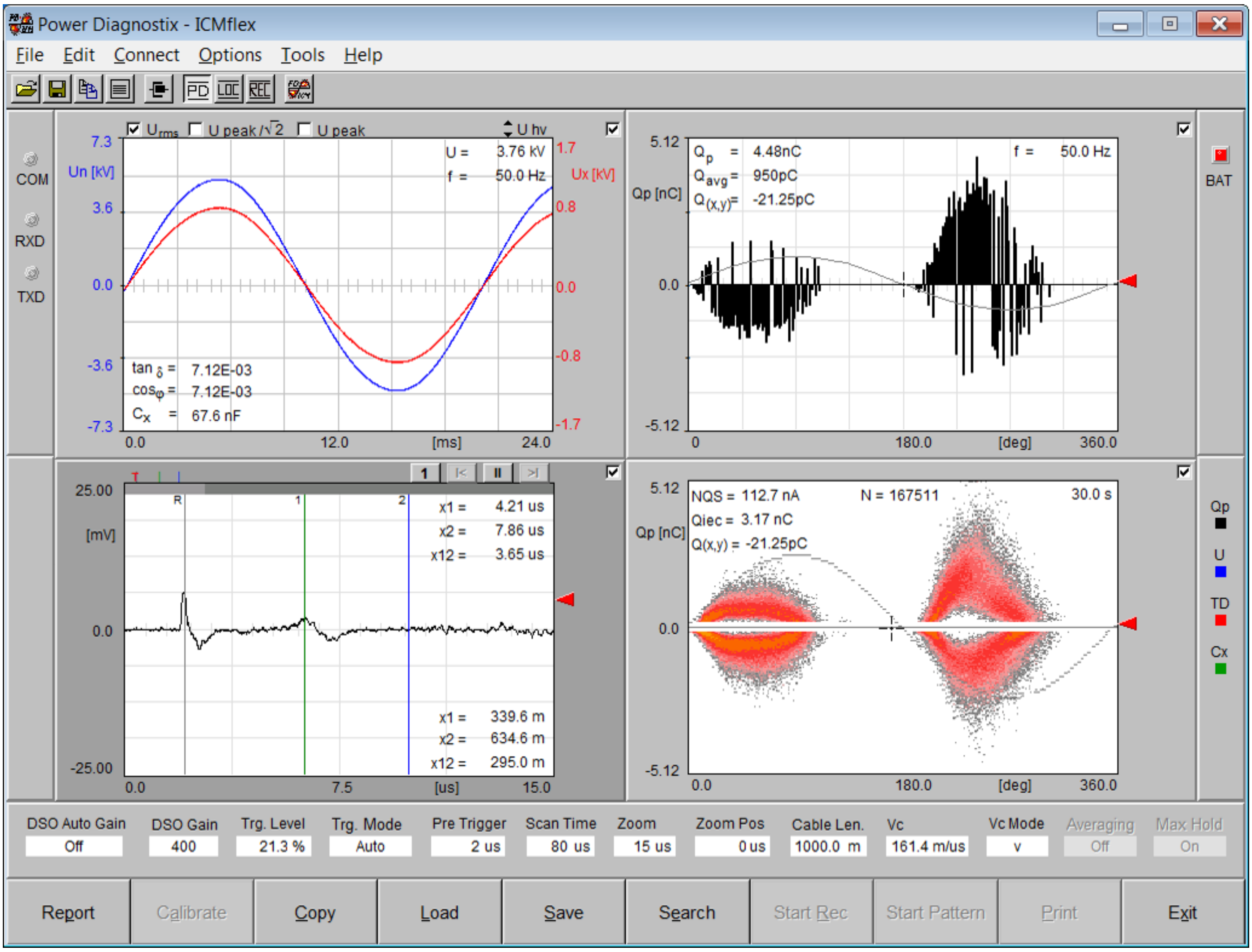


Figure 29: *PD display mode*

The upper left area of the window shows the voltage waveforms (12-bit resolution) for the voltage dividers U_{sn} (reference path) and U_{sx} (specimen path), the voltage and frequency values, and, if supported by the system, the loss factor and capacitance values. The graph in the upper right-hand part of the screen continuously displays a two-dimensional representation of PD activity vs. phase, accumulated over multiple refresh cycles. Additionally, the current PD peak magnitude is shown in the upper left corner of this graph. The magnitude must be calibrated (see application notes in section 7.7). The time domain graph in the lower left area can be used to evaluate single PD events and the reflections of pulses, as detected on medium and high voltage cable insulation systems, on a time-based curve (resolution of 100 Msamples/second). The different cursors help determine the exact fault position and to get precise results. In the lower right area of the windows, a three-dimensional PD pattern acquisition can be initiated and visualised. The phase-resolved PD pattern has a resolution of 8 bits x 8 bits with a 16-bit colour depth and allows further interpretation of failures within the insulation system. As well as the pattern itself, the related discharge levels, set time, and the number of events are shown.

7.4.2 LOC display mode

The LOC display mode is used to perform PD fault location measurements on medium and high voltage cables. An ICM*flex* with the LOC option for cable fault location incorporates a digital storage oscilloscope (DSO) to display partial discharge signals on a time-based curve. Single PD pulses can be triggered with a time resolution of 10 ns (100 Msamples/s) and a maximum display range of 320 µs (firmware version ≥ 1.25) which corresponds to a theoretical maximum cable length of approximately 22 km for a cable with a pulse velocity of 140 m/µs. The DSO panel is at the lower left in PD and LOC mode (see Figure 30). As well as the DSO display, both PD representation charts remain available in upper and lower areas on the right-hand side. In the upper left screen, a summary of the measured reflections versus the position of occurrence along the cable length can be shown.

To perform cable fault location (LOC), the length of the cable and/or the pulse velocity of the cable must be known in advance. Time domain reflectometry (TDR) is based on the travel time of pulses. Since a cable behaves as a wave conductor, the TDR principle can be used to locate sources of partial discharges along the full cable length.

A partial discharge pulse that is caused by an insulation imperfection travels to both ends of the cable. For an open end (no load attached, or high impedance load compared to the cable’s characteristic impedance), a partial discharge pulse occurring somewhere in the cable will, when it reaches the end of the cable, be reflected toward the opposite end. The distance of the PD source to the near and/or far end of the cable can be calculated using the time difference between the arrival times of pulses at the measuring impedance (coupling capacitor).

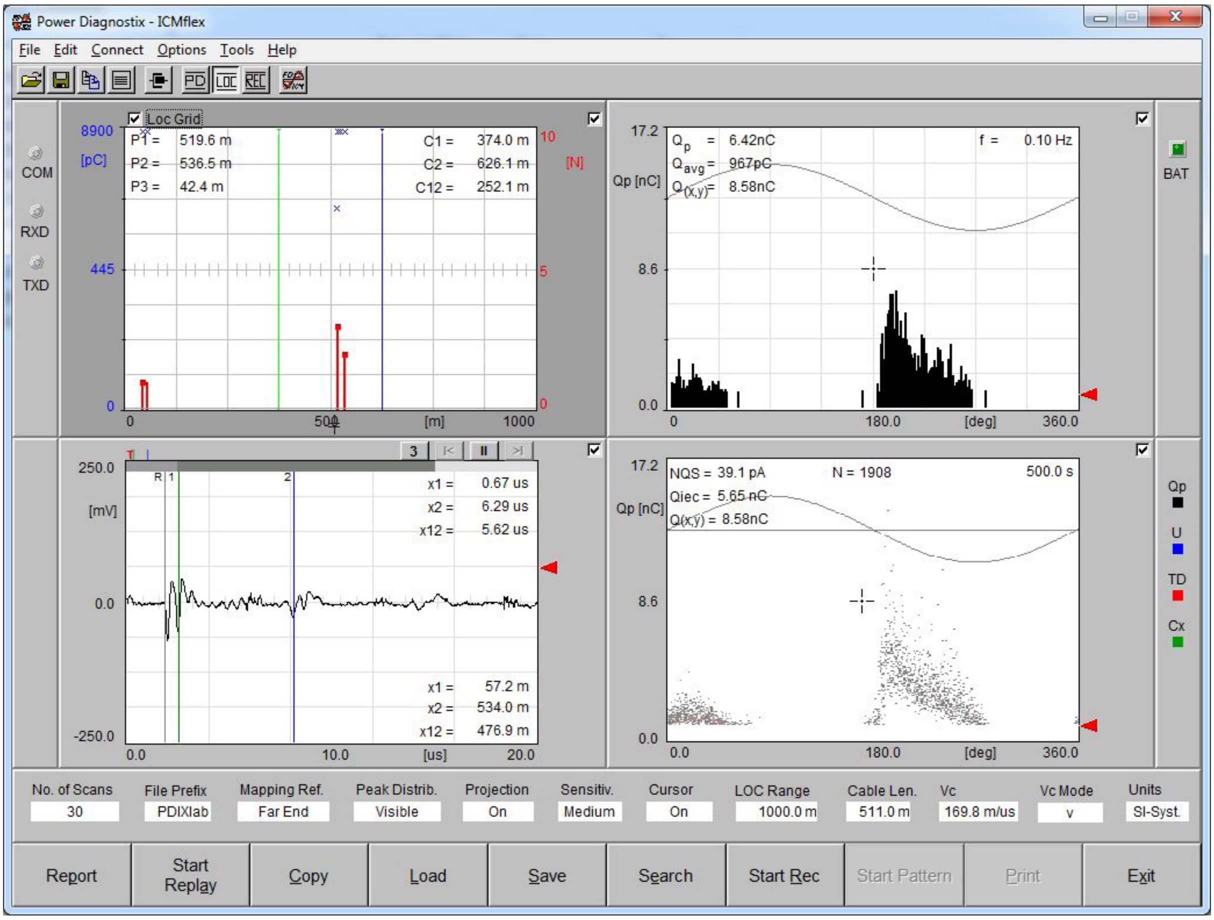


Figure 30: *LOC display mode*

The principle of the time domain reflectometry is illustrated in Figure 31. The travel paths of the first three reflections of the original partial discharge pulse that enter the coupling unit of the ICM*flex* are displayed in different colours.

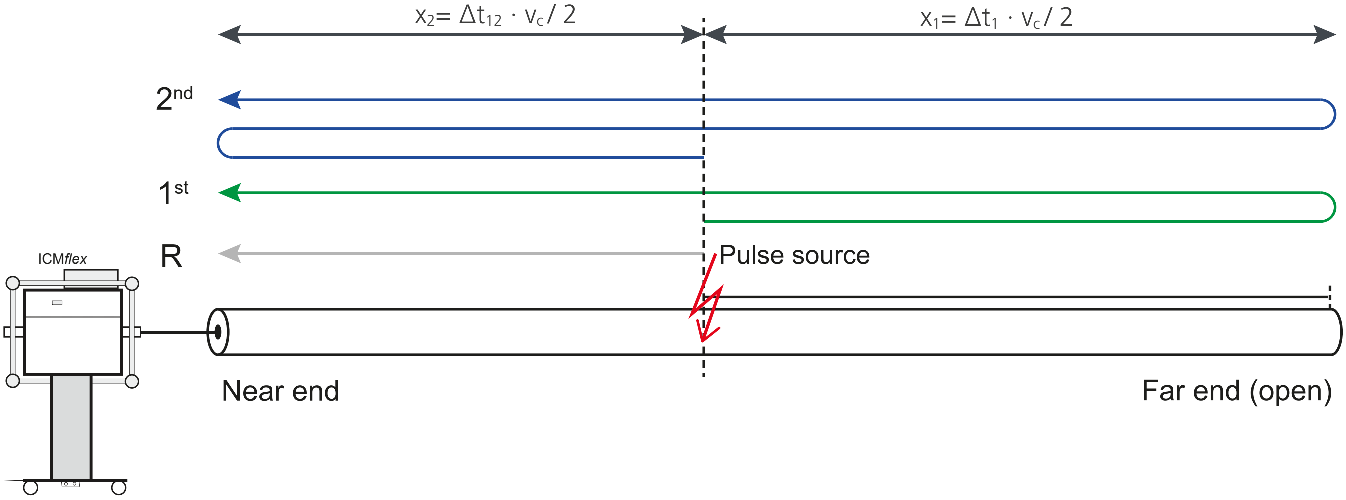


Figure 31: *TDR principle*

In Figure 32, the three impulses are shown as they would appear on the ICM*flex* DSO screen. The reference pulse (R, black cursor) travelled directly from the pulse source to the coupling unit. The first reflection (1st, green cursor) travelled first in the opposite direction, away from the coupler and was reflected at the open end of the cable. This resulted in a time delay Δt_1 that indicates the distance of the PD source from the far end of the cable. Finally, the second reflection (2nd, blue cursor) shows the time delay between the reference pulse and its reflection at the far end. The time difference between the first and the second reflection is a time delay Δt_{12} representing the distance of the pulse source from the near end of the cable. See section 4 in the ICM*flex* application guide in for a detailed example.

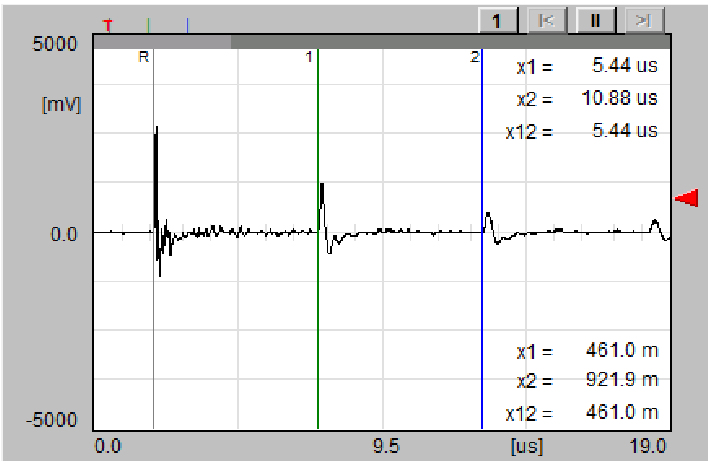


Figure 32: *ICMflex DSO screen*

7.4.3 REC display mode

The REC display mode is used to show results in a summarising table or graph. The collected data can be displayed vs. time or vs. voltage. The voltage graph in the upper left area remains unchanged. The strip chart at the upper right-hand side always shows the actual measurement readings, while the lower left chart shows the values from the data table at the lower right. Figure 33 shows the data plotted against voltage. By changing the setting of the X-axis to “vs. Time”, the values will be shown as a function of time. The table gives an overview of voltage, tan delta, and tan delta tip-up, the specimen capacitance, and the peak discharge level at the moment of triggering.

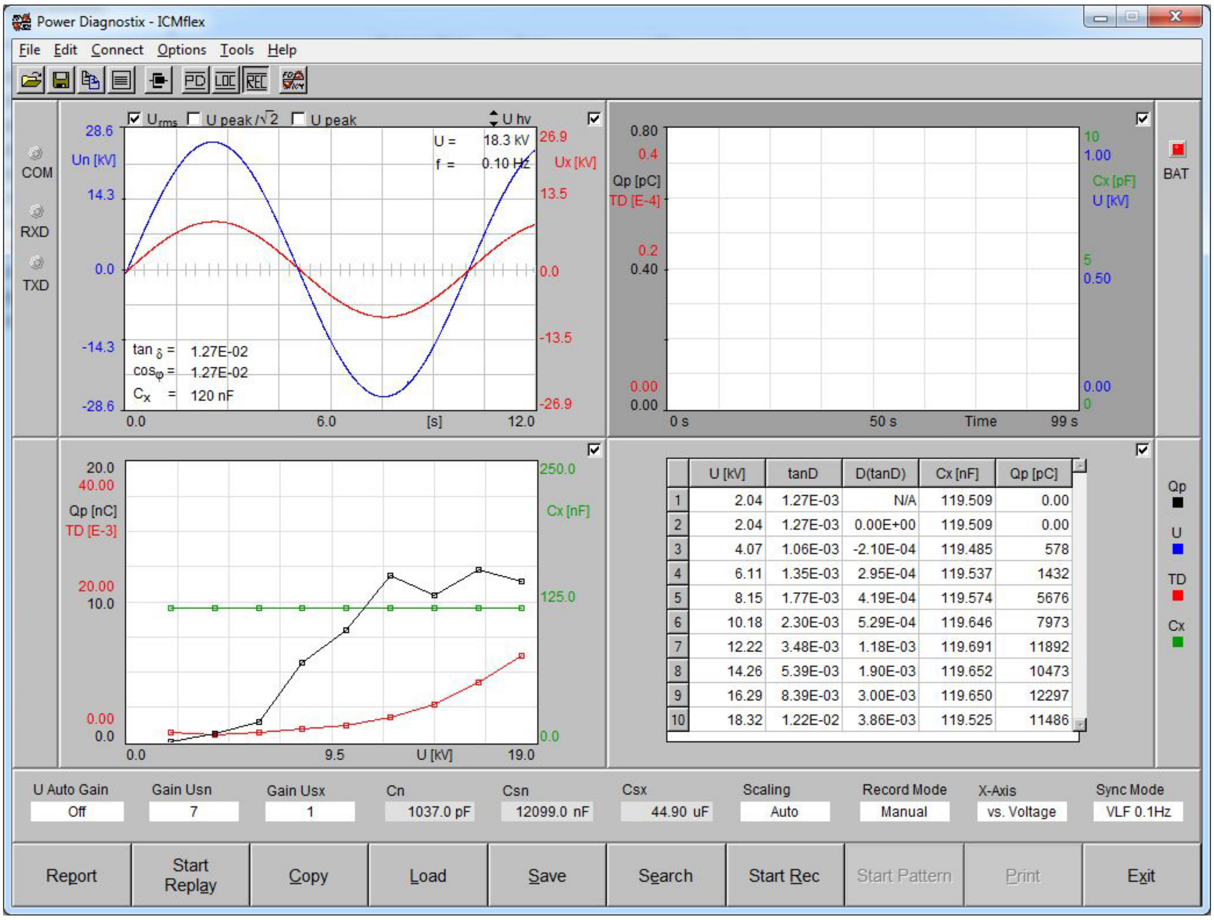


Figure 33: *REC display mode*

The strip charts in the corner on the upper right and lower left sides show:

- Green: Capacitance of the sample under test (Cx)
- Blue: Supplied voltage level (U), as RMS, peak, or peak/√2
- Black: PD magnitude in pC (Qp)
- Red: Loss factor (TD)

With each data refresh from the instrument, the latest values are shown in the two upper charts. A full measurement can be recorded manually or automatically by defining a measurement sequence.

When using manual mode, the measurement is started by pressing the “Start Rec” button. To store readings, the “Trigger” button is used, when the required voltage step is reached. Relevant data, such as the applied voltage, tan delta, tan delta tip-up value, capacitance, and apparent charge levels, will be registered and show as graph versus voltage or time in the lower left of the screen.

An automatic trigger mode is included and is selected by setting the record mode to “Sequence”. The “Trigger” button changes to “Sequence” and allows the measurement sequence to be defined. The desired voltage steps can be entered manually via the panel for the manual sequence or can be calculated for the automatic sequence after entering the specimen’s ratings.

Additional settings needed are the voltage tolerance between the measured and the desired voltage levels, the number of values to be triggered at each voltage step, the time to stabilise before conducting any readings, and the period between consecutive values (capture interval) at a fixed voltage step. Once a sequence is defined, it can be saved and reloaded for future measurements.

Besides recording with a manually defined sequence, the software also offers an automatic sequence mode, which can be edited, as shown in Figure 34. Here, the required voltage steps are calculated automatically according to the specimen voltage, which can be set as the phase-to-phase or the phase-to-ground voltage, and the number of voltage steps.

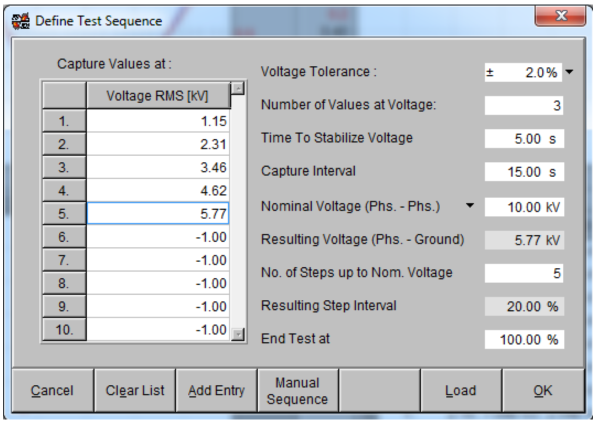


Figure 34: *Automatic sequence wizard*

Depending on the high voltage source and frequency, we recommend selecting appropriate values for stabilisation time and capture interval. At power frequencies, a period refresh takes 16–20 milliseconds, while at very low frequencies a period refresh takes more than 100 seconds. Allow the instrument to complete at least three refreshes to ensure that accurate and useful data is entered into the table.

7.5 Display mode settings

Settings affecting individual graphs or measurements can be found in the lower area of the window above the functional keys. Depending on the graph or area activated (indicated by a dark grey area in the background, e.g., the graph on the lower left-hand side in Figure 35), different settings will be displayed. To toggle between the different set-ups, click once with the left mouse button on the area or graph that you intend to modify.

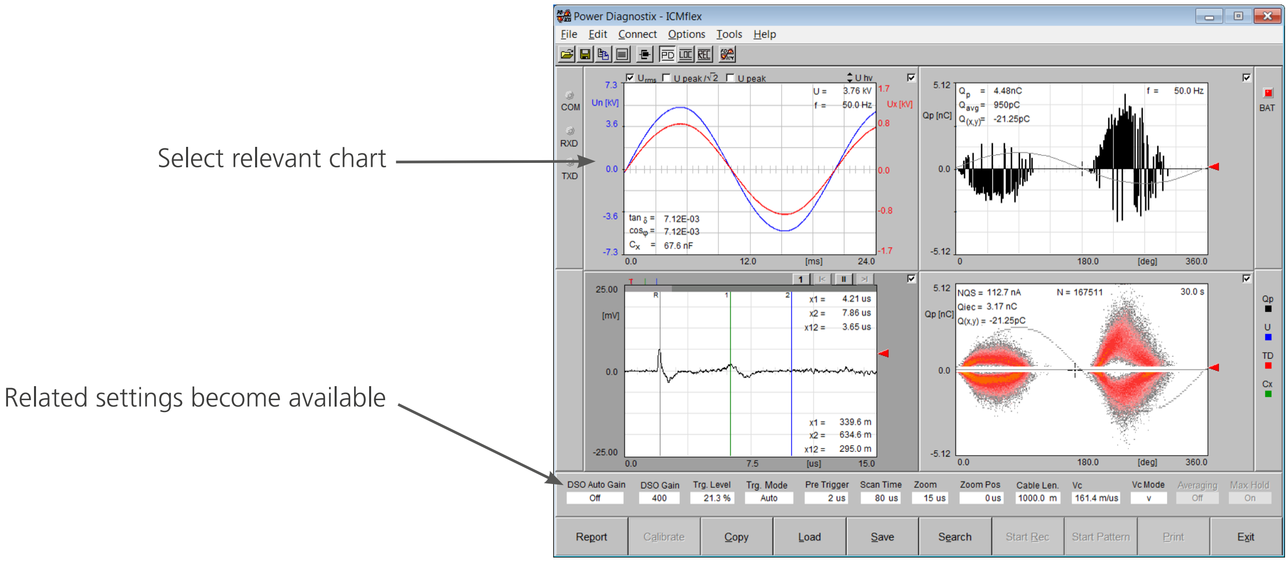
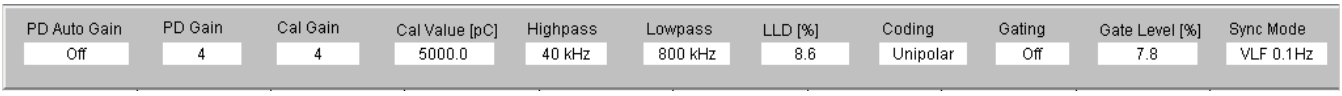


Figure 35: *Chart settings*

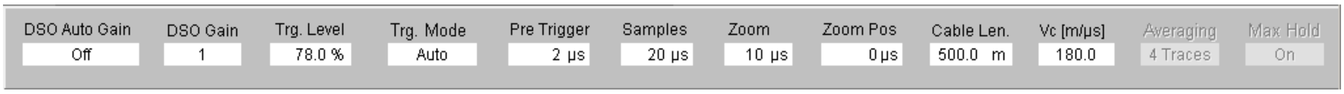
7.5.1 Settings for partial discharge measurement



Setting	Values / Range	Explanation
PD Auto Gain	On/Off	The automatic gain adjustment can help to find the best gain setting for the PD measurement path. If the PD signal reaches 95% of the Y-scale, the software automatically decreases the gain. If the level drops below 10 %, the gain is increased. If the PD level is fluctuating widely, it may be useful to disable automatic mode.
PD Gain	1, 2, 4, 8, 10, 20, 40, 80, 100, 200, 400, 800, 1024, 2048, 4096	The signal amplification can be set manually by selecting a suitable factor from the list. The optimum setting is when the highest peaks are between 60 and 90 % of full scale.
Cal Gain	1, 2, 4, 8, 10, 20, 40, 80, 100, 200, 400, 800, 1024, 2048, 4096	This entry indicates the gain value set during calibration. This value is modified automatically during calibration and cannot be set manually.
Cal Value	1pC–10000 pC	This value has to be set according to the PD level used during calibration.
Highpass	40 kHz, 80 kHz, 100 kHz	Depends on the lower cut-off frequency of the PD bandpass filter.
Lowpass	250 kHz, 600 kHz, 800 kHz	Depends on the upper cut-off frequency of the PD bandpass filter.

LLD	0–100 %	LLD stands for Low Level Discriminator. This is the minimum trigger level for PD pulse acquisition. A level of at least 2 % should be set to eliminate small noise pulses. The level refers to the 100 % full scale of the Y-axis of the PD scope and PD pattern graphs.
Coding	Unipolar/Bipolar	PD pulses can be separated by their polarity. "Bipolar" shows positive and negative pulses separately, whereas "Unipolar" does not consider the polarity.
Gating	On/Off	If gating is enabled (On) it is possible to eliminate external noise pulses. This function is available with all instruments offering an external "Gate In" connector on the acquisition box. The noise signal is taken directly from the HV line input on the HV filter. A special high frequency current transformer must be used.
Gate Level	0–100 %	This trigger level determines the sensitivity of the gate input of the acquisition system. The higher this level is set, the fewer external pulses will be triggered.
Sync Mode	Normal, VLF 0.1 Hz, VLF 0.05 Hz, VLF 0.02 Hz	Normal: The frequency of the applied voltage is calculated automatically in a range between 20 Hz and 510 Hz. VLF: The frequency is set manually to match the frequency setting on the VLF power supply.
Set Time	0..100000 s	Pre-set set time for a PD pattern acquisition. The pattern (map) is stopped automatically after expiration of this time.

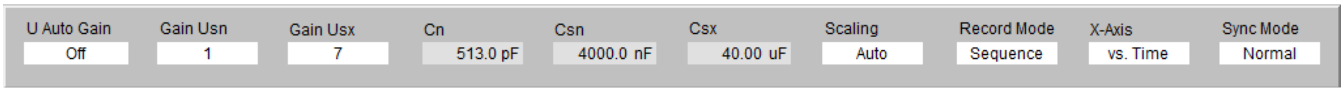
7.5.2 Settings for PD fault location



Setting	Values / Range	Explanation
DSO Auto Gain	On / Off	The automatic gain adjustment can help find the best gain setting for the LOC or DSO graph. If the PD signal rises above 95 % of the Y-scale, the software automatically decreases the gain. If the level drops down below 10 %, the gain is increased. Automatic voltage adjustment is recommended the normal sync mode only.
DSO Gain	1, 2, 4, 8, 10, 20, 40, 80, 100, 200, 400, 800	Amplification factor for the PD signal in time domain.
Trg. Level	0–100 %	Trigger level for high resolution PD pulses in the time domain graph.
Trg. Mode	Auto Normal Single Shot	Auto: This mode continuously displays a signal on the DSO graph (triggered or non-triggered signals). Normal: This mode continuously displays triggered signals only. Single Shot: This mode displays a single triggered PD event and subsequently stops the refresh.
Pre Trigger	1–10 µs	Time on the DSO graph from zero position to the first trigger.
Scan Time	2–320 µs	Total measurement time for PD signals plotted against time (DSO graph).
Zoom	2–320 µs	Zoomed area within the DSO graph. Zooming allows more precise positioning of the cursors.

Zoom Pos	2–320 µs	Zero position of the zoomed area.
Cable Len.	10–25000 m	Length of the cable under test. This length can be calculated during calibration or can be pre-set if the exact value is known.
vc [m/µs] vc/2 [m/µs]	100–200 m/µs 50–100 m/µs	Pulse velocity for PD signals on the MV cable.

7.5.3 Settings for the record mode



Setting	Values / Range	Explanation
U Auto Gain	On/Off	The automatic gain adjustment can help to find the best gain setting for the voltage measurement path. If the voltage signal rises 95 % of the Y-scale, the software automatically decreases the gain. If the level drops down below 10 %, the gain is increased. Automatic voltage adjustment is recommended the normal sync mode only.
Gain Usn	1, 2, 3, 4, 5, 6, 7, 8, 9, 10, 11, 12, 13, 14, 15, 16	Amplification factor for the voltage signal from the shunt capacitor on the reference path; Umax = 20 V_{peak}
Gain Usx	1, 2, 3, 4, 5, 6, 7, 8, 9, 10, 11, 12, 13, 14, 15, 16	Amplification factor for the voltage signal from the shunt capacitor on the test path; U_{max} = 200 V_{peak}
Cn	Stored into device via configuration file **firmware version ≥ 1.26**	Capacitance value of the reference capacitor. Check your system's data sheet or read the value as written on the grey acquisition box.
Csn	Stored into device via configuration file **firmware version ≥ 1.26**	Capacitance value of the shunt capacitor of the reference path. Check your system's data sheet or read the value as written on the grey acquisition box.
Csx (see note below)	No limit; to be calculated before high voltage is applied	Capacitance value of the shunt capacitor of the test path. Check your system's data sheet or read the value as written on the grey acquisition box. With most systems this value is switchable (ext. jumper) between two ranges, e.g. 40 µF/400 µF
Scaling	Auto/Full Range	Y-axis scaling mode for the voltage graph (left upper corner). The voltage waveform is scaled to a maximum in "Auto" mode. The "Full Range" mode sets the maximum of the Y-axis to the maximum value corresponding to the gain chosen.
Record Mode	Manual/Sequence	This mode is important for the record function. In "Manual" mode, the values in the record table are filled for each manual trigger event. The "Sequence" mode fills the values into the table if a pre-set voltage level is reached. The voltage level must be defined in advance.
X-Axis	vs. Time/vs. Voltage	The record graph in the left lower corner can show values versus time or versus voltage.
Sync Mode	Normal, VLF 0.1 Hz, VLF 0.05 Hz, VLF 0.02 Hz	Normal: The frequency of the applied voltage is calculated automatically in a range between 20 Hz and 510 Hz. VLF: The frequency is set manually to match the frequency setting on the VLF power supply.

Note:

The setting of the shunt capacitance value for the test circuit C_{sx} depends on the maximum test voltage. The voltage at the shunt capacitor C_{sx} must not exceed 200 V_{peak} or 140 V RMS.

$U_{x,max} = U_{max} \cdot C_{x,max} / C_{sx} < 140$ V (!)

Select values for C_{sx} according to the test specimen capacitance and the required maximum test voltage (U_{max}). The shunt capacitor values are stored into the device settings via the configuration file provided by Megger. The actual voltages given by dividers U_n and U_x can be shown in the voltage display by selecting U_{acq}. Incorrect selection of the shunt capacitor will result in clipping of the sine wave. Be aware that $U_{n,max}$ must not exceed 20 V_{peak} (14 V RMS) and $U_{x,max}$ must not exceed 200 V_{peak} (140 V RMS). Both values are displayed in the top right-hand corner of the voltage measurement chart (Figure 36).

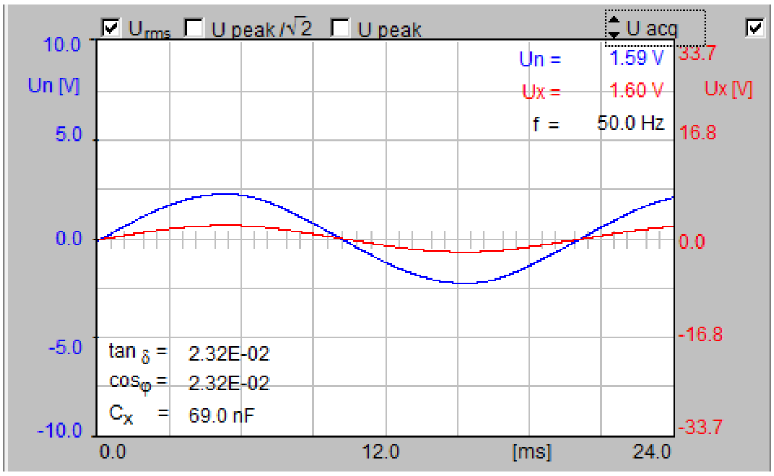


Figure 36: *Voltage measurement chart*

7.6 Functions and menus

The ICM*flex* software offers multiple functions directly from the front panel or via the menu bar at the top of the screen. These functions vary, depending on the display mode chosen and the hardware options available with the instrument.

7.6.1 Menu items

7.6.1.1 File

Standard file functions, such as loading and saving files and setting the default directory, can be selected directly from the “File” menu, as shown in Figure 37. Waveform and/or record exports to an .xls, .xlsx or .html file can also be selected here. After loading the .flx file, the export will be made automatically.

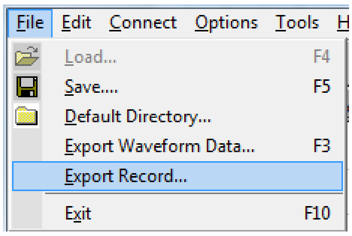


Figure 37: *File menu*

7.6.1.2 Edit

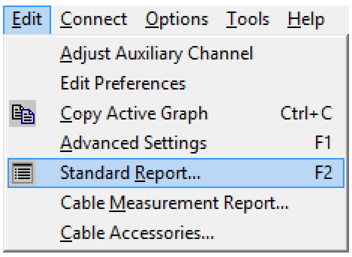


Figure 38: *Edit menu*

The “Edit” menu contains the options for copying the active graph to the Windows clipboard. It also offers access to preferences, advanced settings for the device (Figure 38), report functions, and options for cable accessories (Figure 39).

If the cable is equipped with accessories at a fixed position that is known, such as joints, terminations, and cross-link boxes, these can be shown as a symbol in the summarising LOC graph. The exact position along the cable length and the desired symbol and colour can be set using the “Cable Accessories” option.

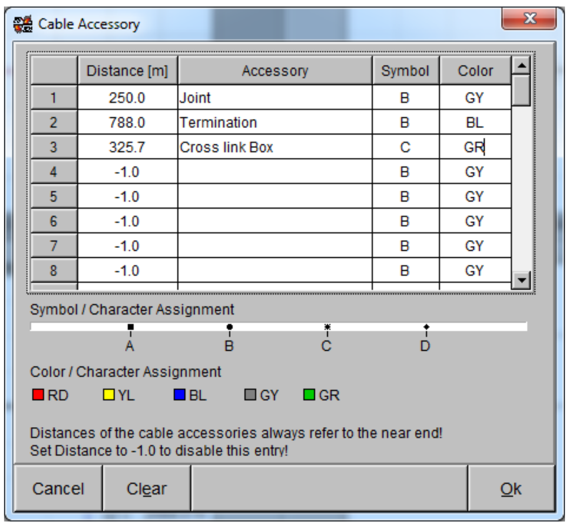


Figure 39: *Cable accessory window*

The software can generate a standard report as explained in section 7.6.2.1 and/or a detailed cable measurement report. The editable options for the detailed report are shown in the screenshot in Figure 40. In general, the measured data included in the reports is similar. The differences are mainly various details concerning the specimen under test, which can be entered, and the cable accessories at known positions along the cable length.

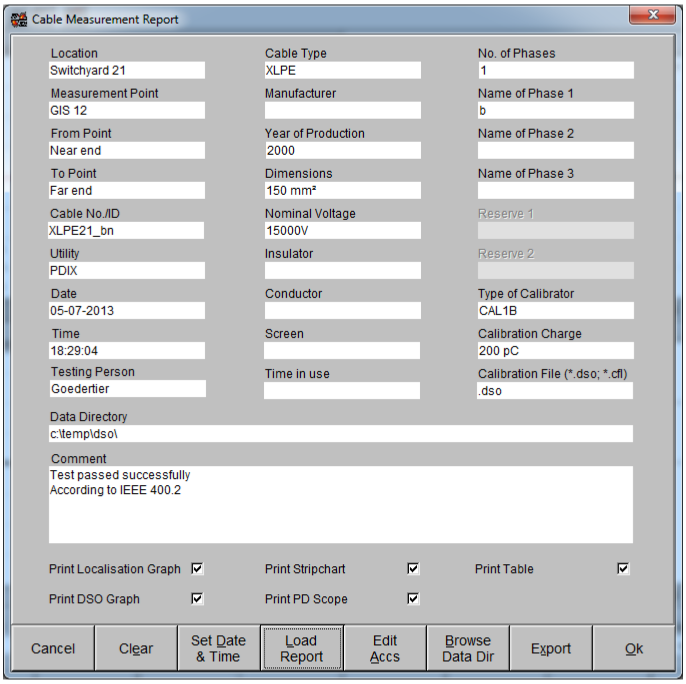


Figure 40: *Cable measurement report window*

General settings, such as interface and report language, display resolution, or the type of window labelling can be made in the "Preferences" window.

"Record Charge Weighting" determines whether the charge weighting follows IEC 60270 (Qiec) or IEC 60034-27-1 (Qm).

"Record PD/inc/ext voltage" enables/disables recording of the inception/extinction voltage.

"Activate TCP Server" enables/disables the ICM*flex* control software's built-in TCP server, which allows third-party programs to access measured values. Connection to the TCP server can be established using the computer's IP address and the port specified in the preferences.

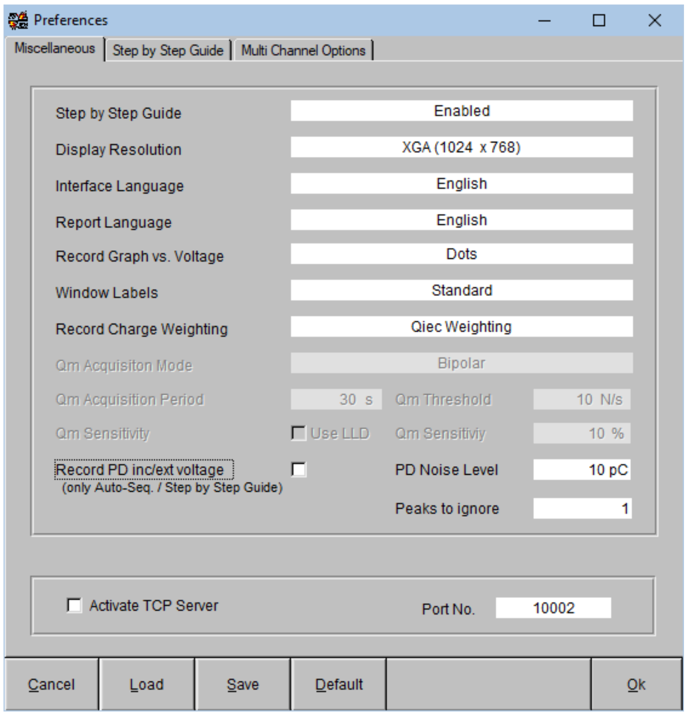


Figure 41: *General preferences windows*

7.6.1.3 Connect

Connection of the software to the ICM*flex* can be established by using the F6 function key, with the menu option as shown in Figure 42, or by pressing the “Search” button in the key bar.

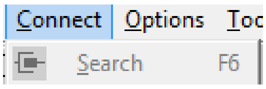


Figure 42: *Connect menu*

7.6.1.4 Options

The “Options” menu (Figure 43) mostly offers settings for the various charts. In addition, the language, display resolution, and the interface settings, as explained in section 7.2, can be selected.

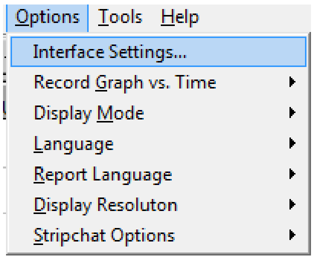


Figure 43: *Options menu*

7.6.1.5 Tools

The “Tools” menu (Figure 44) shows the device information (see Figure 28).

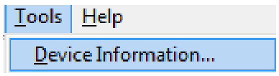


Figure 44: *Tools menu*

7.6.1.6 **Help**

The “About” item of the “Help” menu (Figure 45) gives information about the installed software release as shown in Figure 46. For further questions regarding the device, the Power Diagnostix contact details are given.

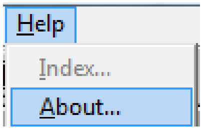


Figure 45: *Help menu*

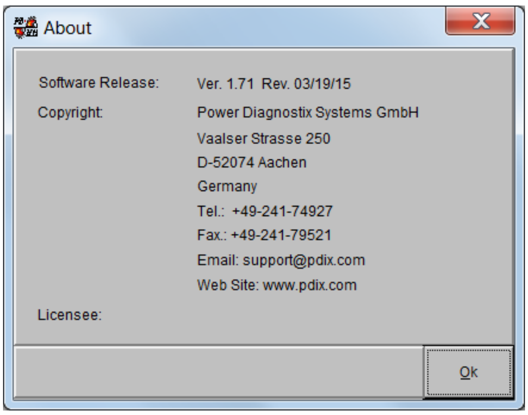


Figure 46: *‘About’ window*

7.6.2 Function keys

All main functions are shown at the bottom of the window (see figure below). Some buttons cover multiple functions depending on the display mode of the software.

Figure 47: *Function keys at the bottom of the application window*

7.6.2.1 Report [F1]

Pressing this button will open the pop-up window shown in Figure 48. Here, it is possible to fill out a standard report with brief information regarding the measurements made. This set of information is saved with each ICM*flex* file (*.flx) and is available after loading files from the hard drive or SSD. It will appear on most printouts and with all exported data, like .html or .xls(x) files. The live charts required for the report can be selected with the tick boxes at the bottom of the panel. Note that the charts used in the reports are always the current charts.

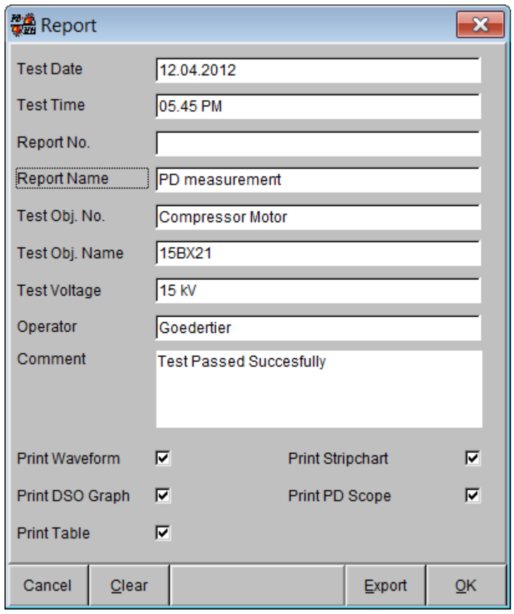


Figure 48: *Standard report*

7.6.2.2 Calibrate [F2]

The “Calibrate” function can be used to calibrate either the PD amplitude or the cable length of an MV cable under test. To calibrate the PD amplitude, it is necessary to activate the PD scope display (graph on the upper right) or the PD pattern display (graph on the lower right). Pressing the “Calibrate” [F2] button in this mode will open a pop-up window where the exact PD calibration value must be entered. This value is equal to the value displayed on the PD calibrator (CAL1A or CAL1B). Check the correct connection of the PD calibrator, the correct gain setting, and the PD pulse on the PD scope display before calibrating. Further explanation is given in the ICM*flex* application guide in sections 4.2 and 5.2. The length of an MV cable can be calibrated by first activating the DSO display (lower left graph). Check the reflections of PD pulses on the graph and set cursor R and cursor 2 to the first and the second pulse. After pressing the button “Calibrate” the software automatically calculates the pulse velocity of the PD pulses.

7.6.2.3 Copy [F3]

This helpful tool copies graphs to the Windows clipboard. Pressing this button will place a copy of the activated graph (panel with dark grey background) into the clipboard, from where it can be pasted into documents in other applications.

7.6.2.4 Load [F4]

This function is available only when the software is not connected to an instrument. It allows old measurements to be loaded from a hard disc or other memory. Files saved with the ICM*flex* software have the file suffix *.flx. This file comprises all measurement data, settings, and reports. To restore typical settings, it is helpful to save some default files for standard set-ups for cables and rotating machines.

7.6.2.5 Save [F5]

In all modes, it is possible to save *.flx files. Old files can be loaded, modified, and saved again. Running measurements can be saved at any time. The saved file consists of all measurement data, settings, and reports.

7.6.2.6 Search/Offline [F6]

To connect the ICM*flex* software to an instrument, press the “Search” button. If the COM port settings and the cabling are correct and the instrument is turned on, a pop-up window will show the message “ICM*flex* found at COM xy”. This message will disappear automatically after a few seconds. To disconnect the communication line, press the same button again. While online, this button is labelled “Offline”. While offline, the button is labelled “Search”.

7.6.2.7 Start Rec / Stop Rec [F7]

This button is used to start a recording of values vs. time. Switch to the TD display mode to see all values recorded in the corresponding graph and in the table. This function has to be started and stopped manually by pressing the F7 button.

7.6.2.8 Start Map/Stop Map [F8]

Use this button to start PD pattern acquisition. The pattern is shown in the graph on the lower. The measurement is stopped automatically at the end of the pre-set “Set Time”. It can also be stopped by pressing the F8 button again.

7.6.2.9 Print [F9]

This button sends the active graph to the default printer.

7.6.2.10 Exit

Close the program by pressing this button.

7.7 ICM*flex* and PD calibration

7.7.1 Calibrators

There is a broad range of impulse generators offered by Megger for different purposes. The table below gives an overview of these. All allow the calibration of PD measurements according to IEC 60270/2000, except the CAL2B/C/D, since these models are not equipped with an injection capacitor to enable calibration on GIS. For the ICM*flex*'s applications, the most common calibrators used are the CAL1B for on-site testing and CAL1A for laboratory purposes.

Calibrator	Range	Output	Frequency
CAL1A	1, 2, 5, 10, 20, 50, 100 pC	Injection capacitor <1 pF	50 Hz (60 Hz)
CAL1B	100, 200, 500 pC, 1, 2, 5, 10 nC	Injection capacitor <100 pF	50 Hz (60 Hz)
CAL1C	1, 2, 5, 10, 20, 50, 100 pC* at 100 pF	Voltage output (50 Ω)	50 Hz (60 Hz)
CAL1D	10, 20, 50, 100, 200, 500, 1000 pC	Injection capacitor <10 pF	50 Hz (60 Hz)
CAL1D	1, 2, 5, 10, 20, 50, 100, 200, 500, 1000 pC	Injection capacitor <10 pF	50 Hz (60 Hz)
CAL1D/EXT	1, 2, 5, 10, 20, 50, 100, 200, 500, 1000 pC	Injection capacitor <10 pF	50 Hz (60 Hz)
CAL1E	0.5, 1, 2, 5, 10, 20, 50 nC	Injection capacitor <500 pF	50 Hz (60 Hz)
CAL1F	0.2, 0.5, 1, 2, 5, 10, 20 nC	Injection capacitor <200 pF	50 Hz (60 Hz)
CAL1G	0.02, 0.05, 0.1, 0.2, 0.5, 1, 2 nC	Injection capacitor <20 pF	50 Hz (60 Hz)
CAL1H	0.5, 1, 2, 5, 10, 20, 50 pC* at **pF	Voltage output (50 Ω)	50 Hz (60 Hz)
CAL1J	10, 20, 50, 100, 200, 500, 1000 pC* at 100 pF 100, 200, 500, 1000, 2000, 5000, 10000 pC* at 1 nF	Voltage output (50 Ω)	50 Hz (60 Hz)
CAL2B	2, 5, 10, 20, 30, 40, 50 V (into RL=50 Ω)	Voltage output (50 Ω)	50 Hz (60 Hz)
CAL2C	2, 5, 7, 10, 12, 15, 17, 20 V (into RL=50 Ω)	Voltage output (50 Ω)	50 Hz (60 Hz)

*with external high voltage capacitor, ** value to be specified by customer

Table 18: *Calibrator overview*

As an example, a type CAL1A calibrator is shown in Figure 49. All calibrators are switched on with the "On/Off" button. Both amplitude (Range) and polarity (Pos/Neg) of the single charge pulse per cycle are displayed and can be adjusted by pressing the two buttons. The instrument is synchronised to line frequency by a photodiode. In case of insufficient pick-up of power frequency light, it will automatically select the internal quartz oscillator (50 Hz and 60 Hz versions available). The "On/Off" button must be pressed for more than one second to switch the pulse generator off, while automatic switch-off occurs after approximately 15 min. Operation time of up to 200 hours is possible with the 9 V lithium battery as the average supply current is approximately 5 mA (quiescent current is negligible). An alkaline battery may be used in place of the lithium battery and will give around 90 hours of continuous operation may replace the lithium battery. A weak battery is indicated by the "LO BAT" sign of the LC display.

WARNING : While changing the battery, be aware of internal parts carrying up to 125 V DC!

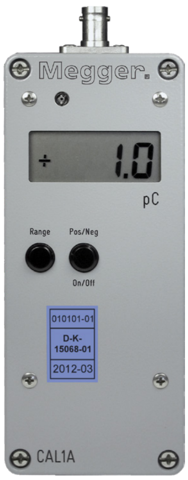


Figure 49: *CAL1A*

Megger delivers its standard calibrators with a fully traceable DAkkS calibration certificate (DK150680100). This calibration certificate documents traceability according to national standards, which fulfil the units of measurement according to the International System of Units SI. The DAkkS (**D**eutsche **Akk**reditierung**s**stelle) is a signatory to the multilateral agreement of the European co-operation for Accreditation (EA) for the mutual recognition of calibration certificates.

Before attaching the calibrator, make sure that the object under test is de-energised. The inner conductor of the BNC/banana adapter must be connected to the test specimen's conductor. The outer (ground) connector has to be connected with the solid grounding of the test object. Ensure that ground leads between the calibrator and the ground shield are as short as possible. Care must be taken that the calibrator is isolated from the HV part of the ICM*flex*.

The charge level to be injected into the measurement circuit depends on the cable length, stator winding or bar capacitance (attenuation), and background noise conditions. It's important to have a good signal-to-noise ratio to ensure a sufficient sensitivity. Choose a value approximately five to ten times higher than the present background noise. Typical values used for on-site testing vary from 200 pC to 5 nC, even 10 nC in the case of very long cable lengths or large turbo generators.

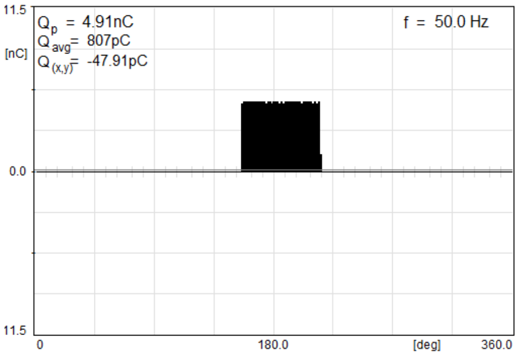


Figure 50: *Calibration pulse scope display*

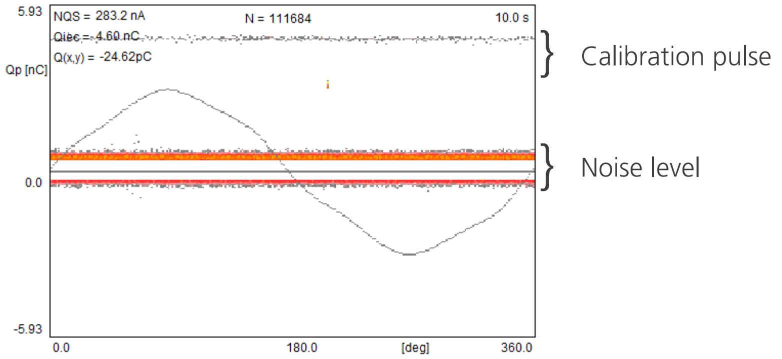


Figure 51: *Calibration pulse PD pattern*

Once the injection value is selected, the calibration pulse can be observed with the ICM*flex* software. Calibration of the apparent charge is supported by the two charts on the right of the PD mode display. The upper left chart represents the calibration pulse as scope like pulse pattern (two-dimensional, compare Figure 50) while the upper right one plots the pulse into an φ-q-n related pattern (three-dimensional as shown in Figure 51). Adjust the PD gain settings so that the calibration pulse fills 60–90 % of the maximum current amplitude. Also, select the appropriate SYNC setting during calibration, CAL50Hz or CAL60Hz, even if VLF is used. Using the same settings for VLF, speeds up the screen refresh. Select a value for the low level discriminator such that the background noise can still be observed. Don't forget to switch off the gating function during calibration.

Calibration can be performed by a double click on the highest pulse shown in the scope-like display or by a double click on the corresponding upper line in the phase resolved PD pattern. Thereafter, the calibration pop-up (Figure 52) will ask for the value of calibration charge. Once this is entered, compensation of the attenuation of the complete circuit will be done automatically. Bear in mind that the calibration is valid for one bandwidth and one specific test set-up only. Hardware and/or software changes require a new calibration. Don't forget to save the calibration file!

Ensure that the selected unit [pC/nC] and amplitude are suitable for the injected charge. For further information about calibration, see sections 4.2 and 5.2 in the applications guide for the ICM*flex*.

WARNING :

- **Always provide solid grounding of the instrument and the filter units**
- **Make sure that the cable/machine is de-energised before calibration.**

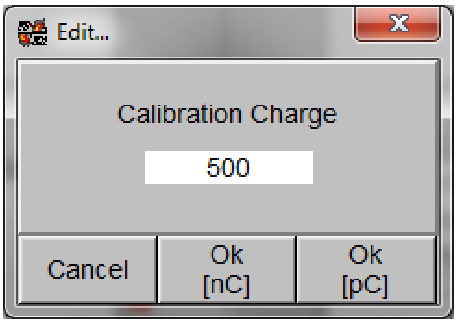


Figure 52: *Calibration charge pop-up*

7.8 Gating

7.8.1 Principle of operation

Effective noise reduction is required when the ICM*flex* is used for measurements in an environment where high frequency (HF) electrical noise is present. HF disturbances that hamper partial discharge detection but can be mitigated by the gating function include frequency converter switching pulses, corona discharge, and thyristor firing, provided those signals from the noise source are picked up by an antenna or another sensor. Using the analogue gating function cuts out this impulse noise. With some applications, a current transformer (CT) is used to acquire the disturbance signal from a ground conductor or from the screen of a signal cable. Some electronically controlled resonant test sets provide a TTL signal for switching purposes.

7.8.2 Analogue gating

The standard ICM*flex* comes with a "GATE IN" terminal for a BNC cable that transmits a gating signal from an HV filter with a built-in current transformer. The gate level is set by using the ICM*flex* software (see section 7.5.1). This option is mainly used for VLF cable testing.

CAUTION : The analogue gating input of the ICM*flex* is intended exclusively for connection to an HV filter! Never connect another device to this input as this may cause serious damage to the equipment.

Analogue
GATE IN

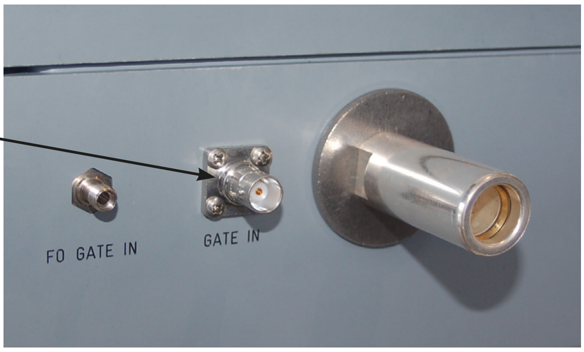


Figure 53: *Gating Inputs*

When using the gating function in the ICM*flex*, disturbance signals from the HV line are detected by the high frequency current transformer (HFCT) embedded in the high voltage filter (T50/1 or equivalent). The output of the HFCT should be connected to the "GATE IN" BNC terminal of the ICM*flex* shown in Figure 53. In the instrument, a built-in pre-amplifier takes care of signal conditioning. The bandwidth for the gating signal is internally set from 2 to 20 MHz. Analogue gating can be activated in the software in the PD Mode (gating on). The gating threshold in percent (gating sensitivity) must be set according to the level of the disturbance pulses. The gate level in percent refers to the maximum scale of the PD pattern or PD scope view at the particular gain. To adjust the gate level to blind out the switching pulses of the VLF for instance, the general background noise must be investigated; the low level discriminator (LLD) level should be set to the peak value of the overall ambient noise. As soon as the LLD level (peak value of the ambient noise) is known, the gate level can be selected at a level above the LLD level to avoid excessive gating times. As soon as the instrument is gating effectively, the corresponding gating time is shown in the PD scope graph (upper graph on the right in PD mode). The gate time in percent refers to the time the instrument gates during one full cycle.

Example:

With 0.1 Hz, one cycle is 10 s, if the gate time is 30 %, gating has been active for 3 s.

In the example shown in Figure 54 and Figure 55, the LLD level was 5 % and the gating threshold was set to 8 %, resulting in a gating time of 7 %, i.e., 0.7 s with a sine wave of 0.1 Hz.

Try to reduce the gate time below 30 % so as not to lose significant PD pulses. In other words, don't set the gating sensitivity too low so that the gate time exceeds 30 to 50 %. Ambient noise other than the switching pulses of the VLF, transformer, or rack transfer switch is not blocked using analogue gating. To deal with other kinds of disturbances, fibre optic gating using the GST1 and a current transformer is available (see section 8.3).

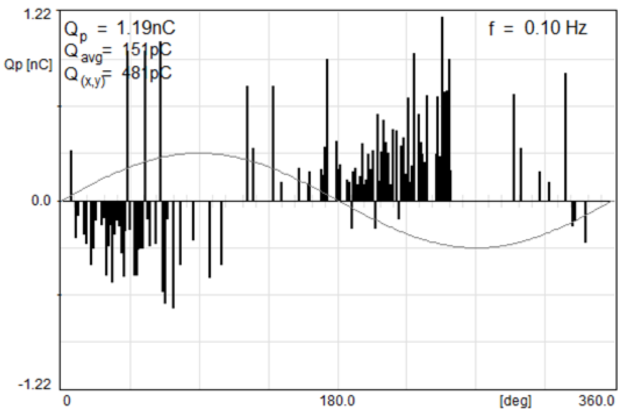


Figure 54: *PD and VLF switching pulses*

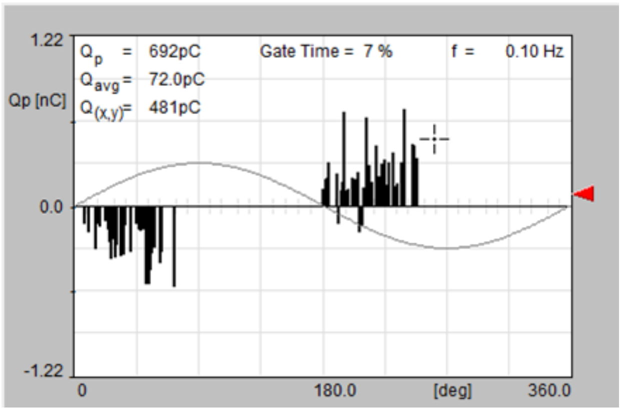


Figure 55: *Switching pulses effectively gated*

8. Options

8.1 Guard Ring Control (GRC)

In order to meet the requirements of the IEEE 286-2000 and IEC 60034-27-3 standards for dielectric dissipation factor testing (also known as tan delta testing) on rotating machine stator bars, Megger upgraded the design of the existing ICM*flex* to produce the ICM*flex* GRC (Guard Ring Control). Both standards require that tan delta testing on stator bars is performed using guard rings to negate the resistive losses of the semi-conductive layer.

Figure 56: *ICMflex GRC*

The guard ring control option provides two driven guard inputs on the ICM*flex* acquisition unit. An internal voltage follower circuit keeps the surface potential of the semi-conductive layer equal to the surface potential of the simulated slot. This means that leakage currents created in the semi-conductive layer flowing from this layer to the straight part of the stator bar are intercepted, and therefore do not influence the dissipation-factor measurement.

The ICM*flex* GRC is optimised for the capacitances of stator bars ranging from small asynchronous induction motors up to the Roebel bars in large synchronous turbogenerators. The embedded voltage divider for up to 30 kV RMS comes with a DAkkS calibration certificate.

The general principle of operation is similar to that of the regular ICM*flex*. It still supports simultaneous PD and tan delta measurement, and hence, the operational software for the ICM*flex* GRC is the same as that for the ICM*flex*. The main difference with the standard unit is that the acquisition unit is at low voltage potential allowing the incorporation of guard rings. Additionally, the battery is now internal. The instrument can operate either from the battery or from the line supply.

8.2 Additional PD input for noise cancellation (ICM*flex*2)

The ICM*flex*2 makes it possible to separate pulses from the test object and pulses from the test voltage source by their polarity. The instrument offers a second PD input, as shown in Figure 57, for PD pulses separated from a quadrupole that is built into the HV filter. Another quadrupole is in the path of the coupling capacitor, in the same position as in the standard ICM*flex*. With this configuration, pulses from the test object and pulses from the test voltage source have opposite polarities (see Figure 59). The acquisition unit looks at the polarity of each pulse and sorts it into either a PD pattern or into a disturbance pattern.

Figure 57: *Additional input for noise cancellation 'PD2 IN'*

With an additional PD input there are some additional options selectable in the preferences panel of the ICM*flex* software. These are shown in Figure 58. The user can determine if different filter configurations should be used for the main and the auxiliary channel (not recommended) and whether or not these two channels should use the same configuration. “DSO & Scope View” determines the behaviour of the software when changing the channel during acquisition, while “Pattern Acquisition” shows, which channel is used for the acquisition of a PD pattern. It is also possible to change the gating time or use the default value of 10 µs. The “Circuit attenuation“ setting determines the attenuation difference between the acquisition channel and the disturbance channel so that the gains of the two channels can be matched.

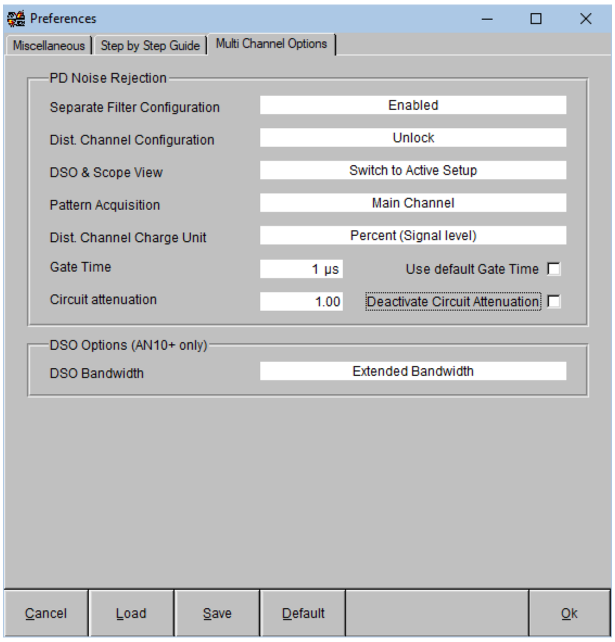


Figure 58: *Multi-channel options*

The “DSO Bandwidth“ can be switched to “IEC 60270“ for optimised time resolution during fault location. The DSO normally operates with an extended bandwidth of 20 MHz.

To determine the polarity, each pulse must be acquired separately. Acquisition is triggered when one of both channels exceeds the low level discriminator (LLD) setting. At this instant, the dead time starts, and at its end, the positive and negative peak amplitudes of both channels are digitised. To achieve t a good pulse separation, both values must be set very carefully. It would be ideal to set the LLD higher than the noise floor, but in order to see the noise floor in the acquisition pattern, it is recommended to set the LLD to a value which allows triggering only on the highest noise pulses. If the LLD is set too low, the acquisition is triggered too often on noise pulses rather than PD pulses. The dead time must be set to the length of the pulse oscillation. If it is set too short, the pulse will not be finished and double triggering can result. If it is set too long, a second pulse may arrive within the dead time, and the smaller pulse will be ignored.

Depending on the ICM*flex*2 configuration, the two quadrupoles may have different sensitivities. In this case, the PD gain must be set separately for the two channels. To compare the sensitivities, the user can switch to the auxiliary channel during calibration and set the gain so that the calibrator pulse amplitude is similar to that of the main channel. The LLD can also be set individually for each channel. To get equal pulse properties on both channels, their high-pass and low-pass settings should be equal. To achieve this, the separate filter configuration can be disabled in the multi-channel options of the preferences (Figure 58).

The ICM*flex*2 functions can be used with the two right-hand screens in the PD and LOC display of the ICM*flex* software. Three additional settings are available with these displays:

Channel: For toggling between the main and auxiliary channel in the screen on the upper right-hand side.

Rejection: Offers three different modes of noise cancellation (“First Pol.“, “Peak Pol.“, and “F&P Pol.“)

Dead Time: Time during which a signal is converted, and which is reserved for a single pulse. The A/D converter will not convert or accept another signal during this time, so additional pulses occurring within the dead time are lost.

In general, there are two different methods of pulse polarity detection. The first is to decide at what polarity the LLD is exceeded first (“First Pol.“). The second is to compare the peak amplitude of both polarities at the end of the dead time (“Peak Pol.“). Additionally, the ICM*flex*2 offers an AND combination of both methods (“F&P Pol.“). The effectiveness of these methods depends on the repetition rate and the amplitude ratio of the two pulse sources. If there is a high repetition rate, the “First Pol.“ method has a problem when a large disturbance pulse follows a smaller PD pulse. If the amplitude of the pulse sources is very different, the “Peak Pol.“ method has a problem; if one pulse is over-ranged in both polarities, the peak amplitudes cannot be compared. Examples of pulse polarity detection are shown in Figure 61 to Figure 64.

Calibration and PD measurement is usually done with the main channel. If “Switch to Active Setup“ is selected for “DSO & Scope View“ within the preferences (Figure 58), the corresponding screens of the PD and LOC display can also show the auxiliary channel, but no calibration is possible, as the amplitude is shown in percent. For the upper right-hand screen, it is possible to choose, whether the scope view displays the acquisition pattern or the disturbance pattern. The lower right-hand screen always shows the acquisition pattern.

To view the shape of the pulses used for the pattern choose “IEC 60270“ for “DSO Bandwidth“ in the multi-channel options of the preferences (Figure 58). In IEC 60270 mode, the DSO shows the filtered signal used for the pattern and the polarity decision. In this mode, only the PD gain is relevant.

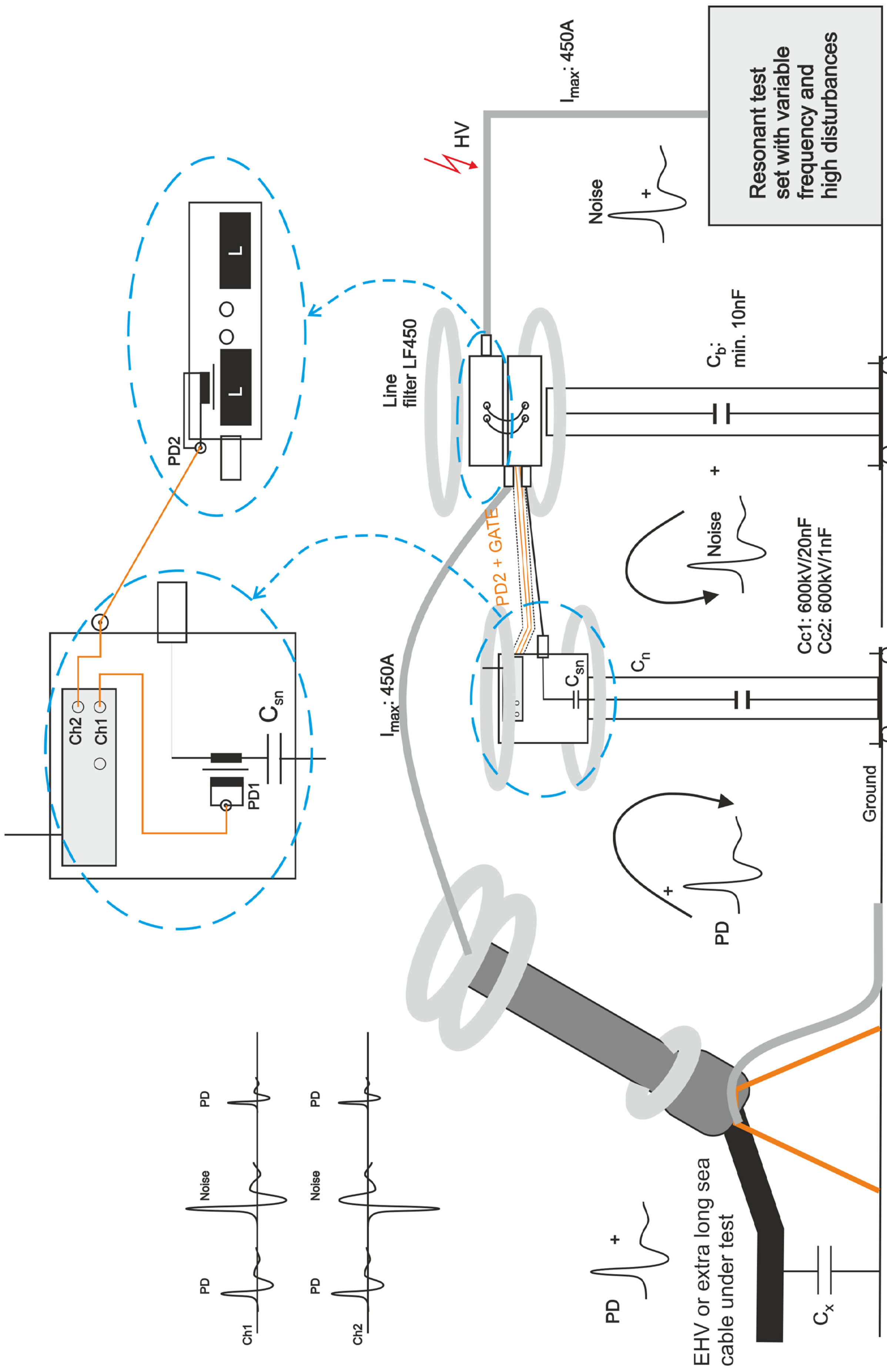


Figure 59: *General connection diagram for ICMflex2*

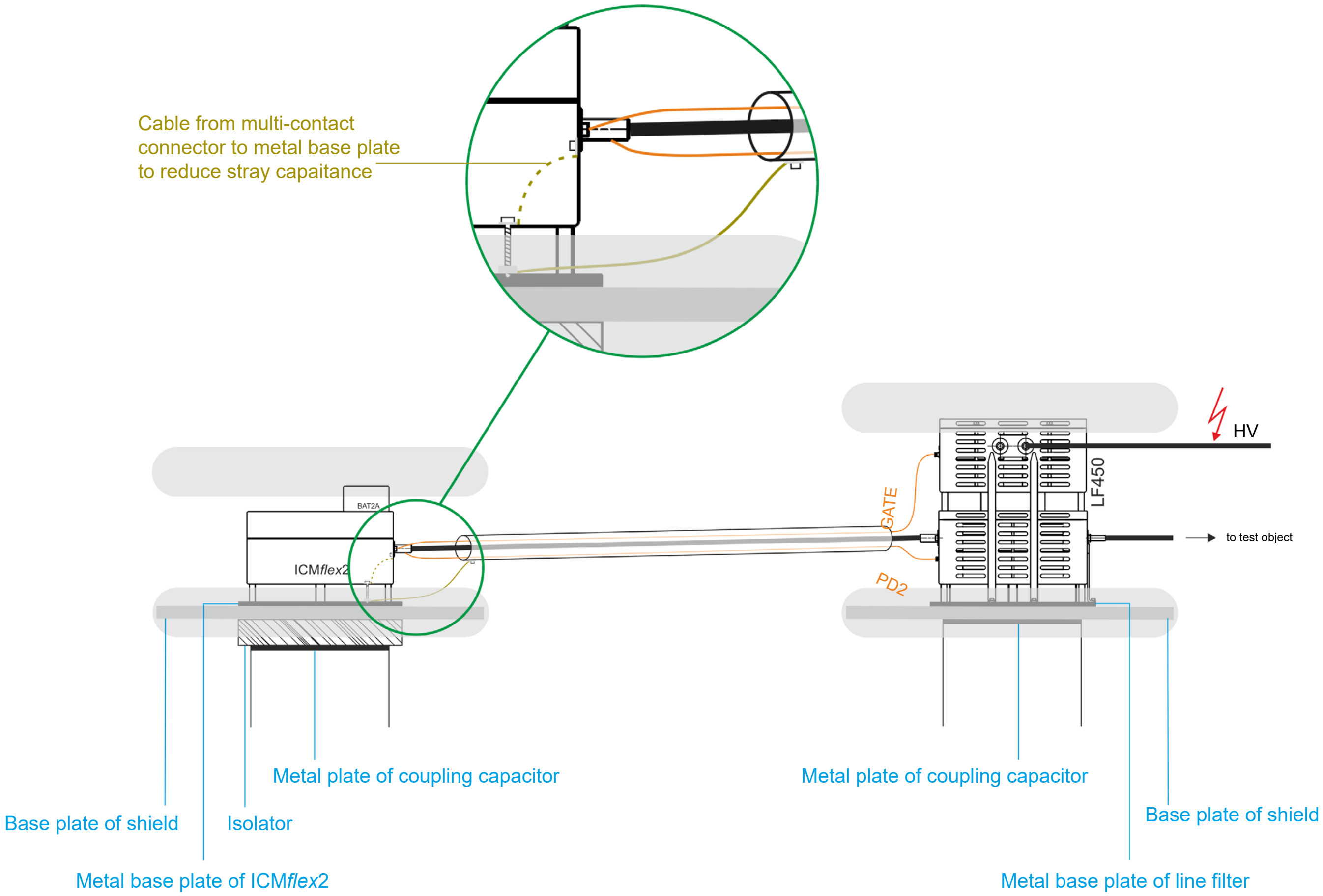


Figure 60: *ICMflex2 and line filter LF450 installed on an external coupling capacitor*

o Polarity of first pulse exceeding the LLD	o Sampled peak values
o Polarity of maximum pulse amplitude	— Peak hold

Pulse from test object

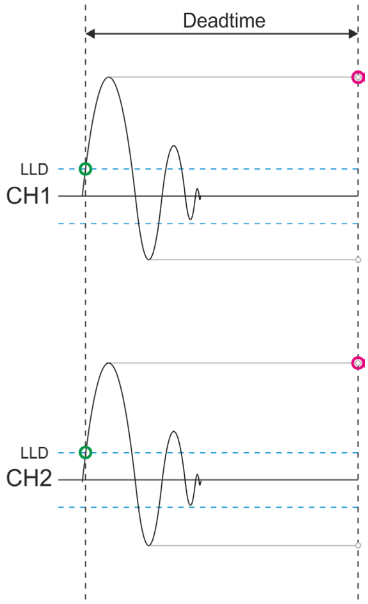


Figure 61: o *and* o *have positive polarity on both channels => 'First Pol.' and 'Peak Pol.' have the same result.*

Pulse from test voltage source

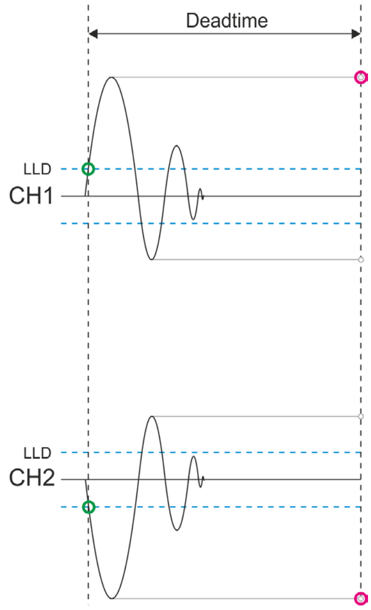


Figure 62: o *positive polarity on channel 1, negative polarity on channel 2;* o *positive polarity on channel 1, negative polarity on channel 2 => 'First Pol.' and 'Peak Pol.' have the same result.*

Pulse from test object followed by larger pulse from test voltage source within deadtime

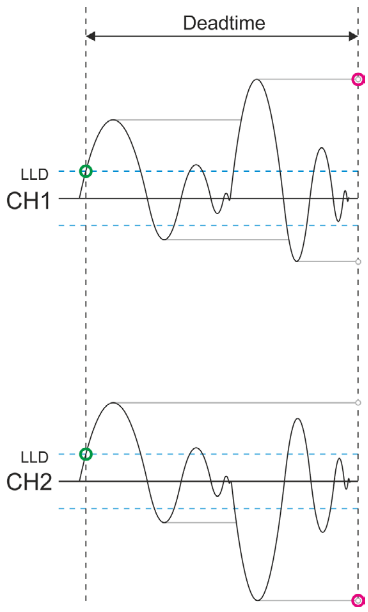


Figure 63: o *Positive polarity on both channels;* o *positive polarity on channel 1, negative polarity on channel 2 => Only 'Peak Pol.' result is correct: Pulse gets sorted into disturbance pattern.*

Pulse from test object with too high amplitude (clipping on both polarities)

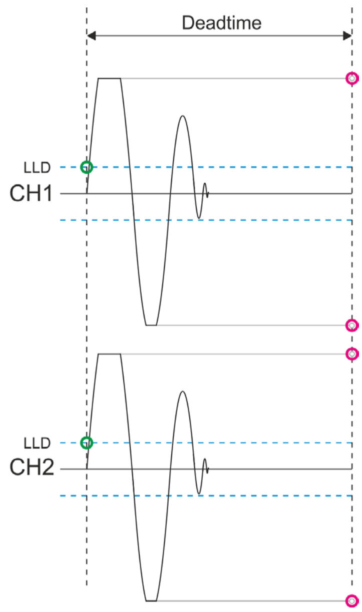


Figure 64: o *Positive polarity on both channels;* o *no decision possible, => only 'First Pol.' result is correct: Pulse gets sorted into disturbance pattern.*

8.3 Gatingv via fibre optic link (FO gating)

An ICM*flex* with an FO gating function has an additional terminal (“FO GATE IN” for a fibre optic (FO) cable, which sends the signal from the gating signal transmitter (GST1) to HV potential. The transmitter is included in the scope of delivery if FO gating is ordered. An external signal sensor (e.g., CT1) is connected via a BNC cable to the “GATE IN” terminal of the GST1.

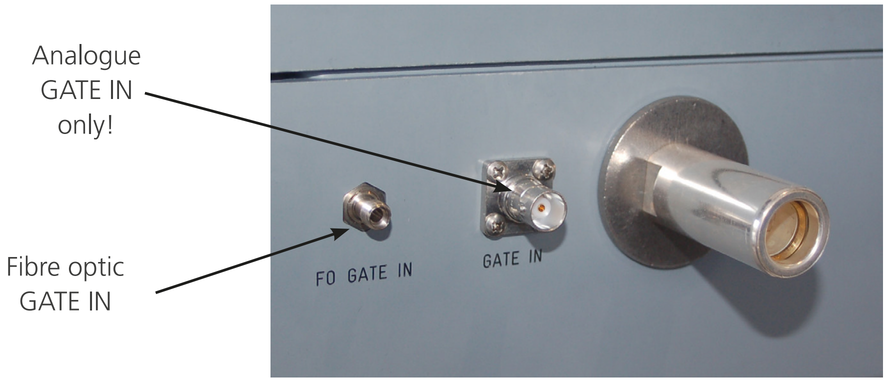


Figure 65: *Gating inputs*

If disturbances like relay switching or thyristor firing have a known source, it might be possible to create a TTL signal relating to the disturbance. This signal can be used to gate the PD measurement path. If a TTL signal is available, it can be connected via a BNC cable to the “TTL IN” terminal of the GST1.

CAUTION : Never connect the GST1’s BNC TTL output to the analogue gating input of the ICM*flex*. This will result in serious damage of the instruments!

FO gating and analogue gating can be used simultaneously.

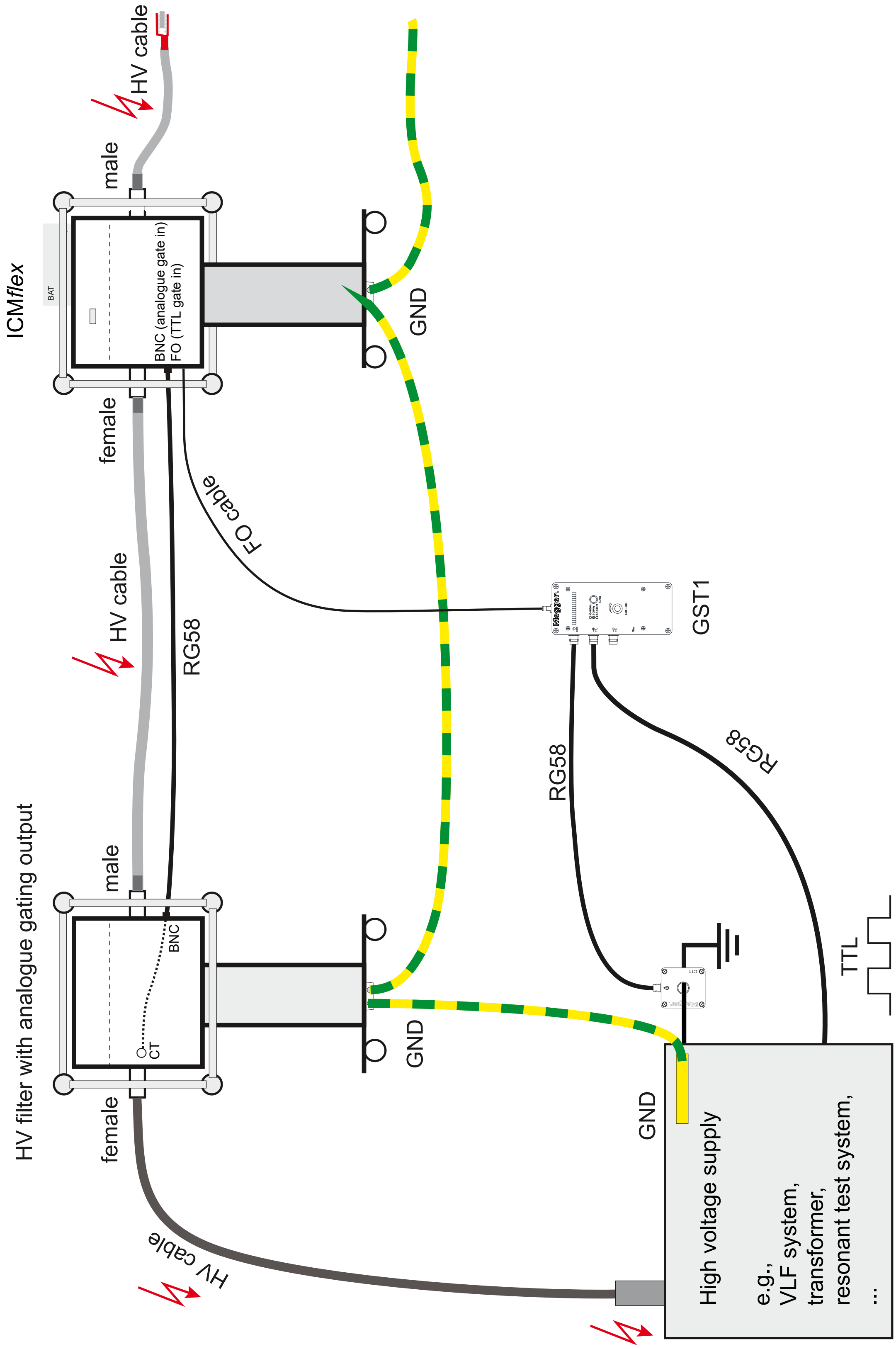


Figure 66: *Gating connection diagram*

The gating signal transmitter GST1 is shown in Figure 67. It offers logarithmic amplification and can be set to three different frequency ranges (40–800 kHz, 2–20 MHz, or 200–600 MHz), which can be selected with a push-button. The active bandwidth mode is shown by a green LED. The gate level can be adjusted with the GST1 rotary switch and is indicated by the orange LED. The level of the analogue signal incoming via "GATE IN" is indicated by the green LED bar. If it exceeds the selected gate level, the bar changes to red. The gate level should be set to the maximum when using a TTL gating signal as the only signal source.

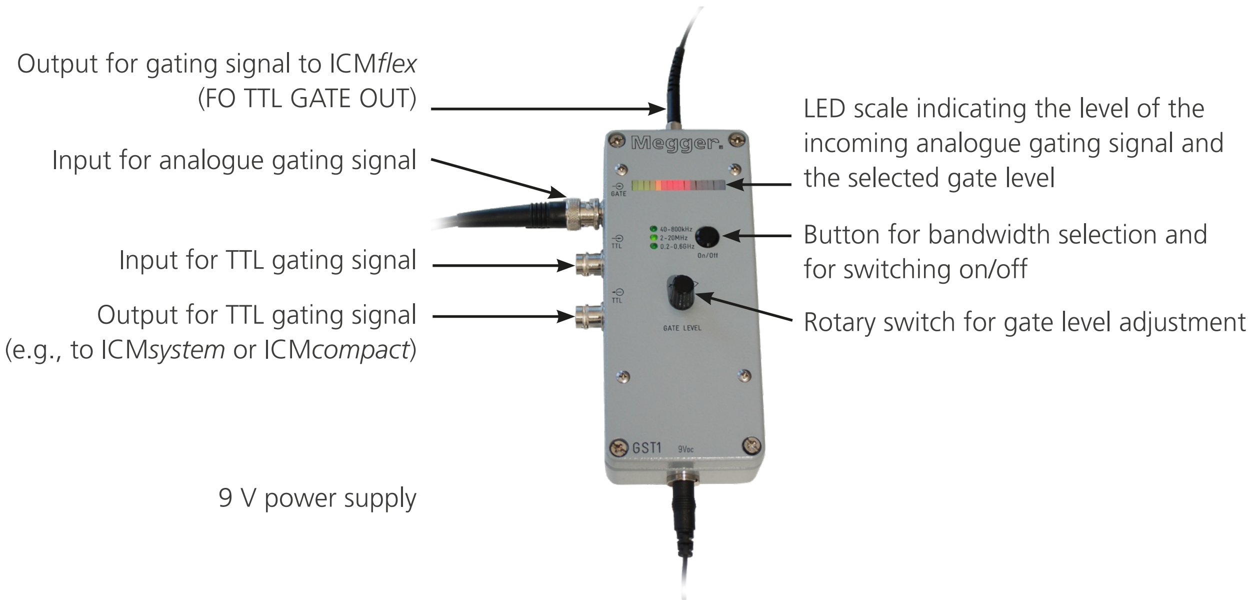


Figure 67: *Gating signal transmitter (GST1)*

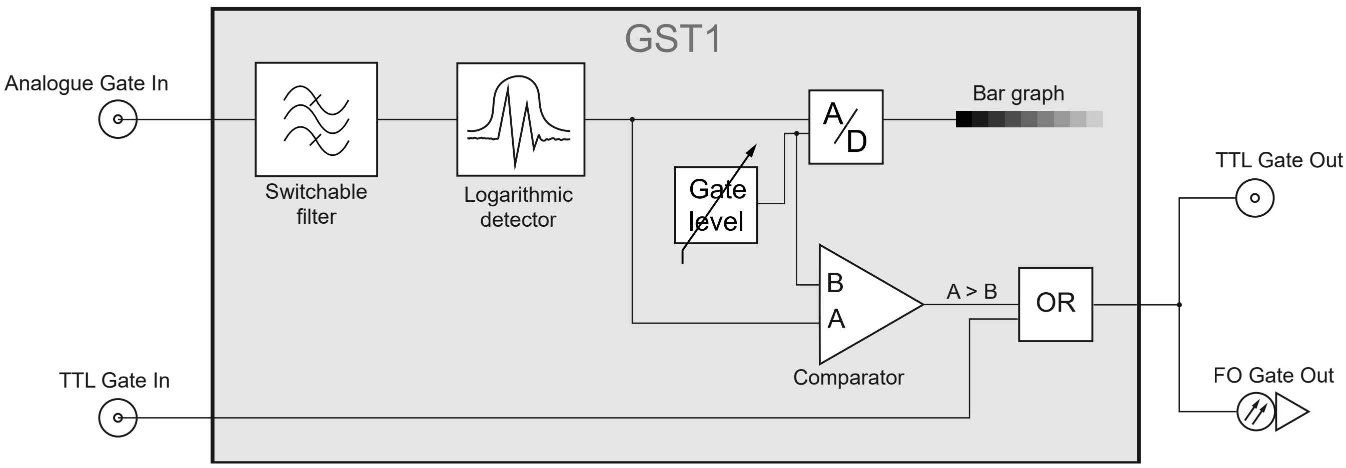


Figure 68: *Disjunction of gating signals when simultaneously using analogue and TTL gating*

8.4 Bypass

If the capacitance of the test object is too high, the ICM*flex* for tan delta measurements can be fitted with a C_{sx} bypass to avoid overstressing of the shunt capacitor. With the bypass active, loss factor measurements are disabled but PD diagnostics are still possible.

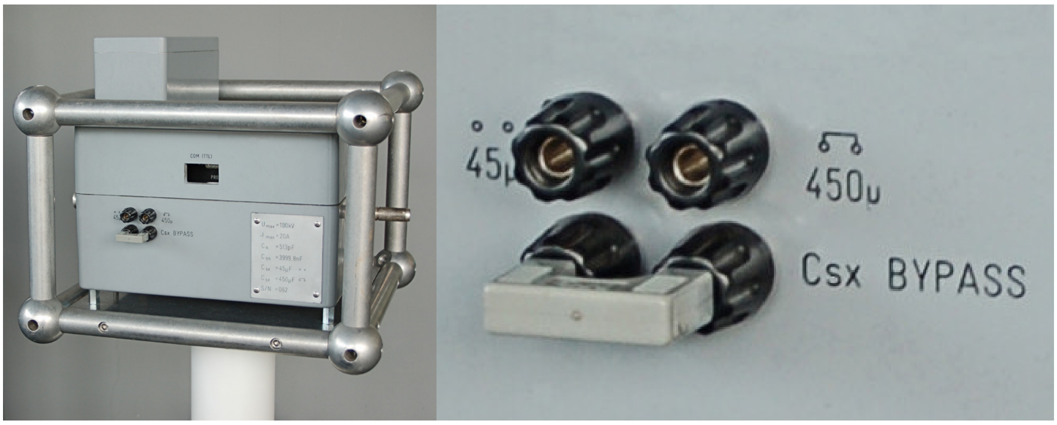


Figure 69: *Jumper in bypass mode*

8.5 Built-in RPA1L

For applications requiring high sensitivity, the ICM*flex* can be fitted with a built-in pre-amplifier (RPA1L), which reduces the instruments input sensitivity to 15 µV. It has switchable pre-gain of 1, 10, and 100. The ICM*flex* with pre-amplifier has an extended gain list (4 to 80000, see Figure 70). From 4 to 100 the pre-gain is 1, from 200 to 1000 the pre-gain is 10, and from 2000 to 80000 the pre-gain is 100. The range of DSO gain is also influenced by the pre-gain, and the total DSO gain cannot be lower than the pre-gain.

If there is an incorrect connection or a short circuit in the cable from the ICM*flex* to the RPA1L, the software shows a warning by changing the background colour of the “PD Gain” setting to red.

If an ICM*flex*2 is equipped with a built-in pre-amplifier, a second RPA1L must to be installed as close as possible to the quadrupole in the HV filter.

Figure 70: *Extended gain list*

8.6 External battery adapter

Megger offers an external battery adapter for connecting larger batteries to the instrument, instead of using the standard ICM*flex* battery BAT2A.

9. Miscellaneous

9.1 Maintenance

The ICM*flex* does not require any maintenance on a regular basis, neither is regular fine adjustment needed, as partial discharge measurement is a relative measurement that is calibrated with a reference source (charge calibrator, CAL series) prior to a measurement. The instrument receives high frequency PD signals and assigns them with a pC level based on the calibration made prior to testing. In case of daily usage, it is recommended to calibrate the impulse generator annually to ensure that its output signal remains within the recommended limits. The only part of the instrument that requires calibration is voltage measurement. Voltage calibration should also be calibrated annually, unless the customer's calibration policy defines a different time interval.

Take care that the instrument stays clean. Any conductive contamination might result into leakage current, which can influence the tan delta measurement results.

9.2 Product marks

This symbol indicates that the marked product should not be disposed of as normal household waste. As it is a B2B product, it may also not be disposed of at civic disposal centres. If you wish to dispose of this product, do so properly by taking it to an organisation specialising in the disposal of old electrical equipment near you.

Any batteries installed must be disposed of separately from the unit.

As a responsible manufacturer, certified according to ISO 14001, Power Diagnostix offers to take back old instruments from its customers. Contact our support team via the Megger web site (www.megger.com) to discuss the procedure for this.

9.3 Transport and shipment instructions

9.3.1 Instrument

In case a unit needs to be returned to the factory, make sure the acquisition unit is packed safely. As the units are relatively small, shipment by couriers, such as DHL, FedEx, or equivalent is the recommended mode of transportation. If possible, declare the instrument as 'used instruments for evaluation' at a relative low value. Consult Megger for further details.

9.3.2 Batteries

If an instrument is suspected to contain a faulty battery module, the module must be removed before the instrument is shipped. Never ship a faulty battery module, either separately or connected to an instrument.

9.4 Declaration of conformity

The manufacturer
Power Diagnostix Instruments GmbH
Vaalser Strasse 250
52074 Aachen
Germany

declares, that the product

ICM*flex*

Partial discharge and loss factor measurement system

provided it is installed, maintained, and operated for the its intended use, in accordance with relevant installation standards and manufacturer's instruction, meets the requirements of the following directive(s):

Low Voltage Directive 2014/35/EU
EMC Directive 2014/30/EU
RoHS Directive 2011/65/EU

It complies with the following standards and/or normative documents:

EN 61010-1:2010
EN 61326-1:2013
EN IEC 63000:2018

9.5 UK declaration of conformity

The UK government has laid legislation to continue recognition of current EU requirements, including the CE marking (Conformité Européene, or European Conformity marking). The legislation will apply indefinitely for a range of product regulations. This means businesses will have the flexibility to use either the UKCA (UK Conformity Assessed) or CE marking to sell products in Great Britain (GB). The message text can be found here: https://www.gov.uk/guidance/using-the-ukca-marking. Megger sells the ICM*flex* in Great Britain using the CE marking.

10. Technical data (standard version)

Mains supply:	Battery operated (up to 6 hours)	
Power requirements:	Approx. 20 VA	
Operation:	Remote controlled via ICM*flex* software	
PD input impedance:	1 kΩ // 50 pF	
PD input sensitivity: (without test object)	< 150 µV, corresponds to 0.2 pC < 15 µV, corresponds to 0.02 pC	(without built-in preamplifier) (with built-in preamplifier; ICM*flex*2 only)
PD lower cut-off (-6 dB):	40, 80, or 100 kHz	(software-controlled)
PD upper cut-off (-6 dB):	250, 600, or 800 kHz	(software-controlled)
PD A/D converter:	8 bits (±7 bits)	
Voltage measurement:	16 bits, 100 kSamples	
Voltage values displayed:	U RMS value, $\hat{U}/\sqrt{2}$ value, crest factor	
Synchronisation:	External on reference voltage	
Synchronisation range:	20–510 Hz 0.1 Hz, 0.05 Hz, 0.02 Hz	(normal mode) (VLF)
Operation temperature:	0–55 °C	(non-condensing)
Interfaces:	Bluetooth Fibre optic serial link	(921 kBit/s) (921 kBit/s)

10.1 Cable fault location

A/D converter:	8 bits
Samples:	100 MSamples
Specimen cable length:	10 to 5000 m, for a sample rate of 320 µs and v_c = 160 m/µs (Localisation on cables longer than 5000 m is not possible because of pulse attenuation)
Localisation precision:	1 m + 0.1 % of the cable length

10.2 Loss factor measurement

Tan delta resolution:	5×10^{-5}
Tan delta precision:	1×10^{-4}

10.3 Weight and dimensions

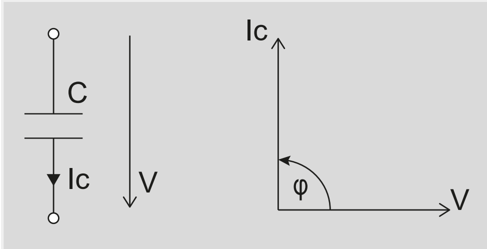
Type	Rated voltage U_r (RMS)	Max. weight kg	Height mm	Width mm	Length mm	Comment
Measurement system						
ICM*flex*	30 kV	22	600	350	350	
ICM*flex*	50 kV	23	800	350	350	
ICM*flex*	100 kV	24	800	350	350	
ICM*flex*	150 kV	60	1600	450	450	
ICM*flex*	>200 kV		-	-	-	To be installed on separate HV reference capacitor of min. 1 nF.
ICM*flex2*	>200 kV		220	365	350	To be installed on separate HV reference capacitor of min. 1 nF.
Filter unit						
T30	30 kV	35	610	350	350	
T50	50 kV	40	800	350	350	
T100	100 kV	46/58	985	350	350	
T150	150 kV	65	1200	350	350	
LF450	-	130	512	450	450	To be installed on separate HV blocking capacitors of min. 10 nF.

11. Appendix

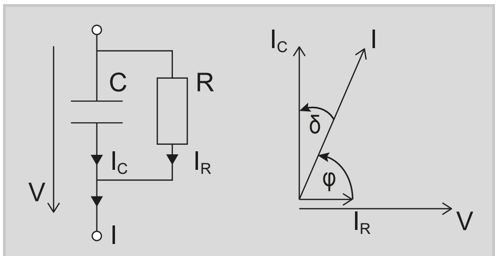
11.1 What is loss factor (or dissipation factor) tan delta?

Building high voltage equipment requires the use of insulating material. Commonly used insulating materials show losses due to resistive currents and polarisation currents of dipoles. Often, the magnitude of these losses can be used as an indicator for the quality of the insulation. In particular, when assessing the quality of aged insulation, increased dissipation indicates oil or paper decomposition (transformers), humidity, electro-chemical processes (water-trees in polymeric cables), or heavy partial discharge.

With an ideal capacitor (C), the resistance of the insulating material (dielectric) is infinite. When an AC voltage (V) is applied, the current (I_C) leads the voltage by exactly phi = 90 °. A component close to this ideal capacitor with negligible resistance should be used as standard (or reference) capacitor for the reference branch of a dielectric loss analyser.



Practical insulation systems are usually built of less than perfect insulating material, resulting in a small current (I_R) in phase with the applied voltage (V). This current can be considered as flowing in a resistor (R) in parallel with an ideal capacitor (C). The phase difference between the actual current (I) and the ideal current (I_C) can be described as phase angle: delta.



Because P = Q · tan delta, where P is resistive power and Q is reactive power, the losses, which are proportional to tan delta, will usually be given as a value of tan delta to express the quality of an insulating material. The angle delta is described as loss angle and tan delta as loss factor.

Loss factor (dissipation factor)

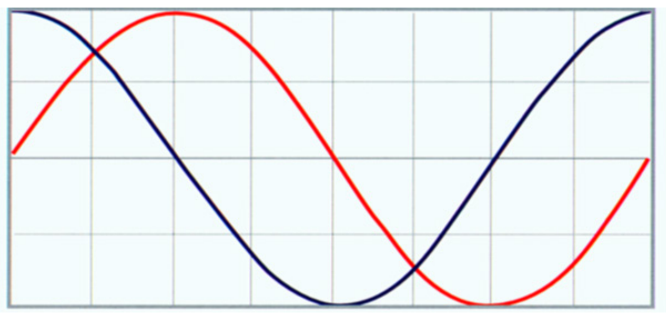
$$\tan\delta = \frac{I_R}{I_C} = \frac{P}{Q} = \frac{1}{\omega \cdot C \cdot R}$$

Quality factor

$$QF = \frac{1}{\tan\delta} = \frac{I_R}{I_C} = \frac{P}{Q} = \omega \cdot C \cdot R$$

Power factor

$$PF = \cos\varphi = \frac{I_R}{I}$$



With the good insulation of low-loss capacitors (delta ~0° and phi ~90°), the actual current (I_C) is approximately equal to the real current (I); resulting in a negligible deviation of the values tan delta and cos phi. In Europe, the dissipation factor tan delta is the most usual figure used to describe dielectric losses, while in North America power factor (PF = cos phi) is commonly used. The ICM*flex* software displays both values, together with the calculated capacitance, the voltages, and the frequency.

11.2 Crimping instructions for multi-contact connectors

11.2.1 Step-by-step instructions

Step 1

Check the set for multi-contact connectors to ensure its complete. A set comprises:

- Two black sleeves
- Two MC connectors
- Two metal insulating sleeves

Figure 71: *MC connector set*

Step 2

Ensure you have an appropriate crimping tool. It must be able to crimp at least 50 mm^2.

Figure 72: *Crimping tool*

Step 3

Put one of the black sleeves over the first cable end.

Step 4

If the cable cross section is more than 16 mm, push the cable end into the smaller part of the multi-contact connector.

If the cable cross section is 16 mm or less, put the small metal insulating sleeve over the cable end and push it with the cable into the smaller part of the multi-contact connector.

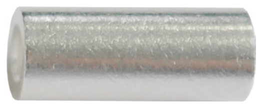


Figure 73: *Metal insulating sleeve for smaller cables*

Step 5

Use the crimping tool to crimp the smaller part of the MC connector two or three times.

Step 6

Repeat steps 3 to 5 for the second cable end.

Figure 74: *MC connector*

WARNING :

- **For protection against electric shock, parts must be isolated from the power supply while being assembled or disassembled.**
- **Connectors may not be connected or disconnected under load.**

11.3 Troubleshooting

The personal computer cannot find the ICM*flex*

If no communication between the ICM*flex* and the software can be established, reboot the control computer and check:

- that all necessary drivers are properly installed (see sections 6.2 and 6.3)
- that the battery is charged (see section 5.3).
  To do this, measure the DC voltage when trying to establish a connection to the ICM*flex*. Connect the battery to the ICM*flex* as shown in Figure 75 (check the polarity first!). If the voltage is 10.5 V or less, the battery has to be recharged. If the voltage drops even after charging for at least six hours, the battery is faulty.

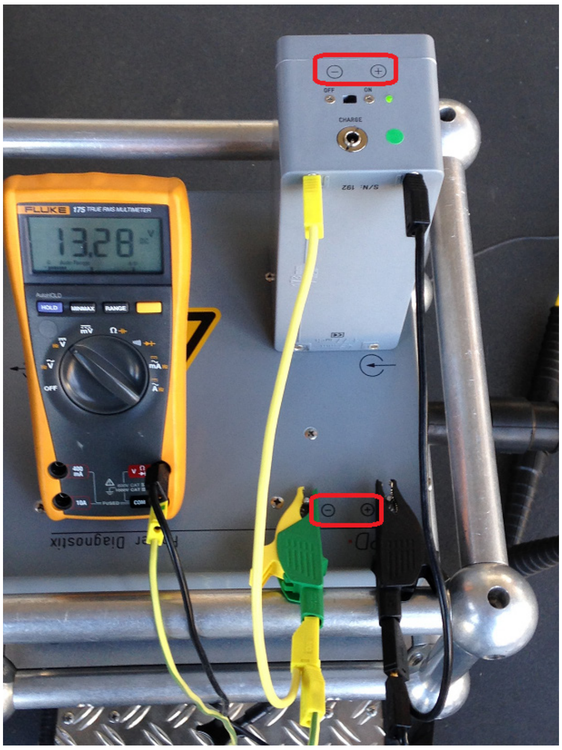


Figure 75: *Testing the voltage of the battery*

The ICM*flex* application window appears very small on high resolution monitors in Windows 10 or Windows 11.

On PCs running Windows 10 with the Creator's Update of 2017 the ICM*flex* application window may appear very small on high resolution monitors. To increase the size of the window, take the following steps:

1. Right-click on the application shortcut on the desktop.
2. Choose "Properties" from the context menu, which will open the "Properties" window (Figure 76).
3. Enable "Override high DPI scaling behaviour" and set "Scaling performed by" to "System" on the "Compatibility" tab.
4. If you have administrator rights, you can change the settings for all users by clicking the corresponding button.
5. Approve the change by clicking "OK".

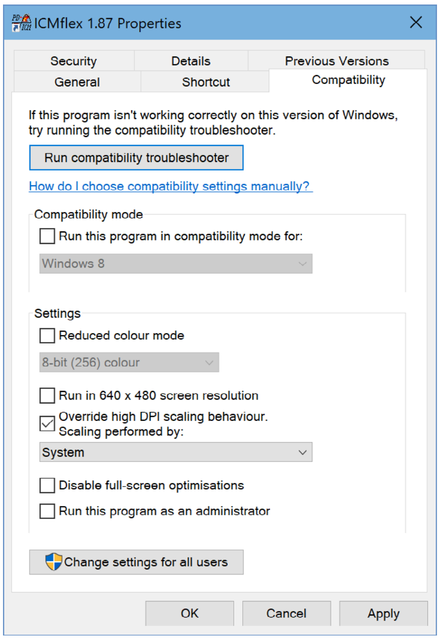


Figure 76: *Properties window*

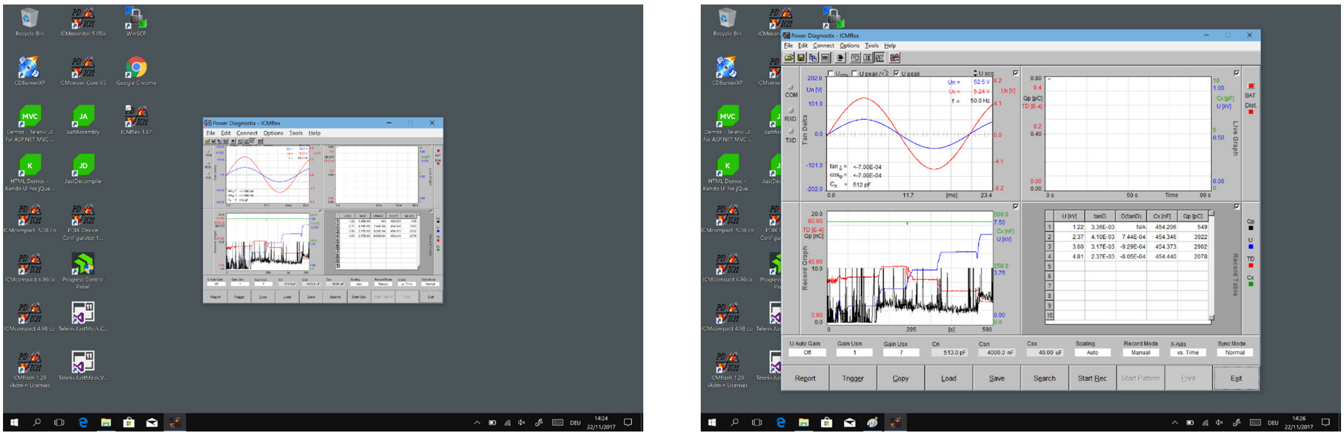


Figure 77: *Desktop before and after changing scaling behaviour*

11.4 National Instruments hardening guide

11.4.1 Introduction

These instructions will guide you through the Megger proposed cyber security operation system hardening after the installation of a National Instruments based software product. The configuration refers only to the Megger software products. If any other third-party National Instruments-based software products are installed or required, the proposed configuration should be adjusted in line with the configuration of the responsible manufacturer.

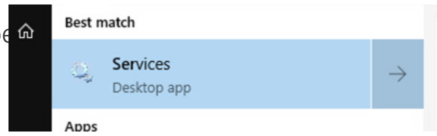
This configuration guide will close three unnecessary National Instruments services. The local ports 3848 UDP and TCP opened by these services will also be closed.

11.4.2 Step-by-step guide

nidmsrv.exe	3848	TCPV6	[0:0:0:0:0:0:0:1]	49672	[0:0:0:0:0:0:0:1]	49673	ESTABLISHED
nidmsrv.exe	3848	TCPV6	[0:0:0:0:0:0:0:1]	49673	[0:0:0:0:0:0:0:1]	49672	ESTABLISHED
nidmsrv.exe	3848	TCP	DESKTOP-Q5NEF6E	59111	DESKTOP-Q5NE...	0	LISTENING
nidmsrv.exe	3848	UDP	DESKTOP-Q5NEF6E	5000	*	*	
nidmsrv.exe	3848	UDP	DESKTOP-Q5NEF6E	6000	*	*	

1.) Open the Windows start menu and type "services.msc".

2.) Click on the search result named "Services". The "Services" window will open.



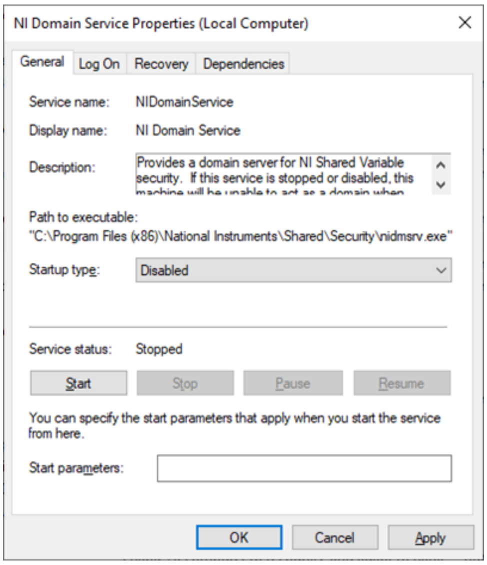
3.) Locate the following in the service list:

- NI Domain Service
- NI PSP Service Locator
- NI Time Synchronization

4.) Open the configuration popup by double clicking each service and change the "Startup type" to "Disabled".

NI Domain Service	Provides a domain server for NI Shared Variable se...	Running	Automatic	Local Syste...
NI PSP Service Locator	Locates servers at the request of network variable c...	Running	Automatic	Network S...
NI Time Synchronization	Allows this machine to keep its time synchronized ...	Running	Automatic	Local Syste...

5.) Save the changes with the button "OK".



11.4.3 Service description

http://www.ni.com/product-documentation/14487/en

NI Domain Service
Service: NIDomainService **Process**: nidmsrv.exe
Description: Provides a domain server for NI Shared Variable security. **If Disabled**: If this service is stopped or disabled, this machine will be unable to act as a domain when configuring shared variable security.

NI PSP Service Locator
Service: lkClassAds **Process**: lkads.exe
Description: Locates servers at the request of network variable clients and other proprietary NI network protocols. **If Disabled**: If this service is stopped or disabled, network variables and network streams will stop working.

NI Time Synchronization
Service: lkTimeSync **Process**: lktsrv.exe
Description: Allows this machine to keep its time synchronized with a master time server, or to act as a time server for other machines. This feature is configured with the Shared Variable Engine settings in LabVIEW. **If Disabled**: If this service is stopped or disabled, this form of time synchronization will not be available.

12. Index

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This equipment is manufactured in Germany.

The company reserves the right to change the specification or design without prior notice.

www.megger.com

ICMflex_UG-M_e1.17